## A FEASIBLE INTERIOR-POINT ALGORITHM BASED ON A KERNEL FUNCTION WITH A HYPERBOLIC BARRIER TERM

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In this work, we present a new primal-dual kernel-based interior-point algorithm for solving linear optimization problems. Our algorithm uses a hyperbolic kernel function to determine the search direction and to measure the distance between the current iterate and the  $\mu$ -center for the algorithm. We study some properties of the kernel function including e-convexity. After that, we derive the iteration complexity of our algorithm for both large- and small-update methods. Finally, we provide some numerical results to show the practical performance of the algorithm in comparison with other existing kernel-based interior-point algorithms.

We are concerned with the standard linear optimization problem defined as follows:

$$(P) \begin{cases} \min c^T x \\ Ax = b, \\ x \ge 0, \end{cases}$$

where  $A \in \mathbb{R}^{m \times n}$ ,  $c \in \mathbb{R}^n$  and  $b \in \mathbb{R}^m$  are given,  $\operatorname{rank}(A) = m \leq n$  and  $x \in \mathbb{R}^n$  is the vector of variables. The dual problem of (P) is given by

$$(D) \begin{cases} \max b^T y \\ A^T y + s = c, \\ s \ge 0, \end{cases}$$

where  $y \in \mathbb{R}^m$  and  $s \in \mathbb{R}^n$  are the vectors of variables. Following the basics of interior-point methods (IPMs), we arrive at the following system

(1) 
$$\begin{cases} A\Delta x = 0, \\ A^T \Delta y + \Delta s = 0, \\ s\Delta x + x\Delta s = \mu e - xs. \end{cases}$$

By taking a step along the search direction, one constructs a new iterate point

$$x_+ := x + \alpha \Delta x, \ y_+ := y + \alpha \Delta y, \ s_+ := s + \alpha \Delta s,$$

for some  $0 < \alpha \leq 1$  satisfying  $(x_+, s_+) > 0$ .

Defining the scaled vector v and the scaled search directions  $d_x$  and  $d_s$  as follows

$$v = \sqrt{\frac{xs}{\mu}}, \ d_x = \frac{v\Delta x}{x}, \ d_s = \frac{v\Delta s}{s},$$

we rewrite system (2) as follows

(2) 
$$\begin{cases} \overline{A}d_x = 0, \\ \overline{A}^T \Delta y + d_s = 0, \\ d_x + d_s = v^{-1} - v, \end{cases}$$

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where  $\overline{A} = \frac{1}{\mu} A V^{-1} X$ ,  $V = \operatorname{diag}(v)$ ,  $X = \operatorname{diag}(x)$ .

A crucial observation is that the right-hand side in the last equation of system (2) is equal to minus gradient of the classical logarithmic scaled barrier (proximity) function

$$\Psi(v) = \sum_{i=1}^{n} \psi_c(v_i),$$

where

$$\psi_c(t) = \frac{t^2 - 1}{2} - \log t.$$

Following the basic of kernel-based primal-dual IPMs, we replace  $\psi_c$  by a new kernel function. The latter belongs to the newly developed hyperbolic type [2,3].

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