LIE-ORTHOGONAL OPERATORS ON METRIC LIE ALGEBRAS

D. R. Popovych¹

¹Institute of Mathematics of National Academy of Sciences of Ukraine, Kyiv, Ukraine ¹Memorial University of Newfoundland, St John's, Canada *dmytro.popovych@imath.kiev.ua*

The condition of Lie orthogonality of operators defined on Lie algebras [1,2] naturally arises in the course of the study of certain structures connected to Lie algebras such as Kähler manifolds and Clifford structures. Here we extend the results obtained in [3] for semisimple and reductive algebras to general metric algebras, see [4, Chapter 3] for a detailed presentation.

Definition 1. A linear operator J on a Lie algebra \mathfrak{g} is called *Lie-orthogonal* if [Jx, Jy] = [x, y] for any $x, y \in \mathfrak{g}$.

Lie-orthogonal operators can be classified up to the following equivalence [3]:

Definition 2. We call Lie-orthogonal operators J and \tilde{J} on a Lie algebra *equivalent* if the image of their difference is contained in the center of this algebra.

Lemma 1. Let \mathfrak{g} be a finite-dimensional centerless Lie algebra that decomposes into the direct sum of its ideals $\mathfrak{i}_1, \ldots, \mathfrak{i}_k, \mathfrak{g} = \mathfrak{i}_1 \oplus \cdots \oplus \mathfrak{i}_k$. An operator J is Lie-orthogonal on \mathfrak{g} if and only if it can be represented as $J = J_1 \oplus \cdots \oplus J_k$, where for any $i = 1, \ldots, k$ the operator J_i is Lie-orthogonal on \mathfrak{i}_i . If the center of the algebra \mathfrak{g} is nonzero, then the same representation holds up to the equivalence of Lie-orthogonal operators.

Recall that a Lie algebra \mathfrak{g} is called a *metric algebra* if there exists a nondegenerate symmetric invariant bilinear form B(x, y). Classical examples of metric Lie algebras are

- semisimple algebras, for each of which the respective Killing form is, up to a nonzero multiplier, the only such form,
- abelian algebras, for which every symmetric bilinear form is trivially invariant,
- reductive algebras as direct sums of semisimple and abelian ones.

For other examples of metric Lie algebras, see Example 1.

Lemma 2. Any Lie-orthogonal operator on any metric Lie algebra is equivalent to one which is annuled by the polynomial $x^2 - 1$.

Theorem 1. Let \mathfrak{g} be a finite-dimensional metric Lie algebra, and J a Lie-orthogonal operator on \mathfrak{g} . Then there exists a decomposition of \mathfrak{g} into a direct sum of two ideals \mathfrak{i}_+ , \mathfrak{i}_- : $\mathfrak{g} = \mathfrak{i}_+ \oplus \mathfrak{i}_-$ such that the operator J is of the form

$$J = \mathrm{id}_{i_+} \oplus (-\mathrm{id}_{i_-}) + J_{\mathfrak{z}},\tag{1}$$

where $J_{\mathfrak{z}}$ is an operator on \mathfrak{g} with image in the center \mathfrak{z} .

Corollary 1. Lie-orthogonal operators on any simple Lie algebra are exhausted by the trivial operators $id_{\mathfrak{g}}$ ma $-id_{\mathfrak{g}}$.

Corollary 2. Let \mathfrak{g} be a finite-dimensional semisimple Lie algebra, and $\mathfrak{g} = \mathfrak{i}_1 \oplus \cdots \oplus \mathfrak{i}_p$ be its decomposition into simple components. Then any Lie-orthogonal operator J on \mathfrak{g} is of the form $J = J_1 \oplus \cdots \oplus J_p$, where for every $s = 1, \ldots, p$, either $J_s = \mathrm{id}_{\mathfrak{i}_s}$ or $J_s = -\mathrm{id}_{\mathfrak{i}_s}$.

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Combining Lemma 1 with Corollary 2 gives a complete description of Lie-orthogonal operators on reductive Lie algebras.

Corollary 3. Let \mathfrak{g} be a finite-dimensional reductive Lie algebra, and $\mathfrak{g} = \mathfrak{z} \oplus \mathfrak{i}_1 \oplus \cdots \oplus \mathfrak{i}_p$ be its decomposition into center and simple components. An operator J on \mathfrak{g} is Lie-orthogonal if and only if it has the form $J = J_0 \oplus J_1 \oplus \cdots \oplus J_p + J_{\mathfrak{z}}$, where for every $s = 1, \ldots, p$ either $J_s = \mathrm{id}_{\mathfrak{i}_s}$ or $J_s = -\mathrm{id}_{\mathfrak{i}_s}$, J_0 is a zero operator on \mathfrak{z} , $J_{\mathfrak{z}}$ is any operator on \mathfrak{g} with image in the center \mathfrak{z} .

Example 1. The four-dimensional non-abelian metric real Lie algebras are the two reductive algebras $A_1 \oplus sl(2, \mathbb{R})$ and $A_1 \oplus so(3)$ and two indecomposable solvable algebras, the oscillator algebra $A_{4.9}^0$ and the diamond algebra $A_{4.8}^{-1}$; see their commutation relations, e.g., in [4] or [5]. Theorem 1 implies that the set of Lie-orthogonal operators on each of these algebras is

$$\left\{ \begin{pmatrix} a_1^1 & a_2^1 & a_3^1 & a_4^1 \\ 0 & \varepsilon & 0 & 0 \\ 0 & 0 & \varepsilon & 0 \\ 0 & 0 & 0 & \varepsilon \end{pmatrix} \middle| \varepsilon = \pm 1, \ a_1^1, a_2^1, a_3^1, a_4^1 \in \mathbb{R} \right\}.$$

Remark 1. Metric Lie algebras do not exhaust all Lie algebras Lie-orthogonal operators on which necessarily admit the decomposition (1). Consider the nonmetric Lie algebra $\mathfrak{g} = \mathfrak{sl}(2,\mathbb{C}) \in_{\rho_1} 2\mathfrak{g}_1$, where ρ_1 is the standard irreducible representation of $\mathfrak{sl}(2,\mathbb{C})$ in the two-dimensional vector space. Up to the skew-symmetry of the Lie bracket, the nonzero commutation relations of this algebra in the canonical basis are exhausted by

$$\begin{split} [e_1,e_2] &= 2e_2, \quad [e_1,e_3] = -2e_3, \quad [e_2,e_3] = e_1, \\ [e_1,e_4] &= e_4, \quad [e_2,e_5] = e_4, \quad [e_3,e_4] = e_5, \quad [e_1,e_5] = -e_5, \end{split}$$

i.e., e_1 , e_2 and e_3 constitute a basis of a Levi factor of \mathfrak{g} , which is isomorphic to $\mathrm{sl}(2,\mathbb{C})$, and (e_4, e_5) is a basis of the abelian radical \mathfrak{r} of \mathfrak{g} . It is proved in [4, Proposition 3.53] that Lie-orthogonal operators on \mathfrak{g} are exhausted by the trivial operators $\mathrm{id}_{\mathfrak{g}}$ tra $-\mathrm{id}_{\mathfrak{g}}$.

Proposition 1. Let J be a Lie-orthogonal operator on a finite-dimensional Lie algebra \mathfrak{g} with the eigenvalue $\lambda = 1$ and \mathfrak{i}_1 be the ideal corresponding to this eigenvalue. Then the restriction J_1 of the operator J on the ideal \mathfrak{i}_1 can be represented, up to equivalence of Lieorthogonal operators on \mathfrak{i}_1 , in the form $J_1 = \mathrm{id}_{\mathfrak{i}_1} + N$, where N is a nilpotent operator on \mathfrak{i}_1 and the image of N is contained in the radical \mathfrak{r}_1 of the ideal \mathfrak{i}_1 .

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