

## $\eta$ -(SKEW) HERMITIAN REFLEXIVE SOLUTION TO A SYSTEM OF REAL QUATERNION MATRIX EQUATIONS

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Let  $\mathbb{R}$  and  $\mathbb{H}^{m \times n}$  stand respectively to the real number field and the set of all  $m \times n$  matrices over the quaternion algebra

$$\mathbb{H} = \{a_0 + a_1i + a_2j + a_3k \mid i^2 = j^2 = k^2 = ijk = -1, a_0, a_1, a_2, a_3 \in \mathbb{R}\}.$$

A matrix  $A \in \mathbb{H}^{n \times n}$  is said to be a  $\eta$ -(skew) Hermitian if  $A = A^{\eta*}$  ( $A = -A^{\eta*}$ ) for  $\eta \in \{i, j, k\}$ . Motivated by [1, 2], in this paper we establish necessary and sufficient conditions for the existence of  $\eta$ -(skew) Hermitian reflexive solution of the system of quaternion matrix equations :

$$\begin{cases} AX = C \\ XB = D \\ NXN^{\eta*} = A_3 \end{cases} \quad (1)$$

and also provide the general expressions of solutions when this system has a solution. In addition, we give some results about the existence of the  $\eta$ -(skew) Hermitian reflexive solution of some classical linear systems.

**Definition 1.** Given a generalized reflection matrix  $P \in \mathbb{H}^{n \times n}$  i.e.  $P^* = P$  and  $P^2 = I_n$ .

1. A matrix  $A \in \mathbb{H}^{n \times n}$  is said to be an  $\eta$ - Hermitian reflexive matrix with respect to  $P$  if  $A = A^{\eta*}$  and  $A = PAP$ .
2. A matrix  $A \in \mathbb{H}^{n \times n}$  is said to be an  $\eta$ - skew-Hermitian reflexive matrix if  $A = -A^{\eta*}$  and  $A = PAP$ .

We denote the set of all  $n \times n$   $\eta$ -Hermitian ( $\eta$ -skew-Hermitian) reflexive matrices with respect to  $P$  by  $\mathfrak{h}\mathbb{H}_r^{n \times n}(P)$  ( $S\mathfrak{h}\mathbb{H}_r^{n \times n}(P)$ ).

The main result of this work is the following.

**Theorem 1.** *Given a generalized reflection matrix  $P \in \mathbb{H}^{n \times n}$ . Let  $A \in \mathbb{H}^{m \times n}$ ,  $B \in \mathbb{H}^{n \times l}$ ,  $C \in \mathbb{H}^{m \times n}$ ,  $D \in \mathbb{H}^{n \times l}$ ,  $N \in \mathbb{H}^{q \times n}$  and  $A_3 = A_3^{\eta*} \in \mathbb{H}^{q \times q}$  for  $(\eta \in \{i, j, k\})$  be given. We put*

$$E = \begin{bmatrix} A_1 \\ B_1^{\eta*} \end{bmatrix}, F = \begin{bmatrix} C_1 \\ D_1^{\eta*} \end{bmatrix}, G = \begin{bmatrix} A_2 \\ B_2^{\eta*} \end{bmatrix}, H = \begin{bmatrix} C_2 \\ D_2^{\eta*} \end{bmatrix},$$

$$K = C_3L_E, J = D_3L_G, M = R_KJ, S = JL_M,$$

$$Q = A_3 - C_3E^+FC_3^{\eta*} - C_3F^{\eta*}(E^+)^{\eta*}C_3^{\eta*} - D_3G^+HD_3^{\eta*} - D_3H^{\eta*}(G^+)^{\eta*}D_3^{\eta*} \\ + C_3E^+EF^{\eta*}(E^+)^{\eta*}C_3^{\eta*} + D_3G^+GH^{\eta*}(G^+)^{\eta*}D_3^{\eta*}.$$

Then, the following statements are equivalent:

- 1) The system (1) has a  $\eta$ - Hermitian reflexive solution  $X \in \mathfrak{h}\mathbb{H}_r^{n \times n}(P)$ .
- 2)

$$EF^{\eta*} = FE^{\eta*},$$

$$GH^{\eta*} = HG^{\eta*},$$

$$R_EF = R_GH = R_MR_KQ = R_KQ(R_J)^{\eta} = 0.$$

3)

$$\begin{aligned}
 & r \begin{bmatrix} A_1 & C_1 \\ B_1^{\eta^*} & D_1^{\eta^*} \end{bmatrix} = r \begin{bmatrix} A_1 \\ B_1^{\eta^*} \end{bmatrix}, \\
 & r \begin{bmatrix} A_2 & C_2 \\ B_2^{\eta^*} & D_2^{\eta^*} \end{bmatrix} = r \begin{bmatrix} A_2 \\ B_2^{\eta^*} \end{bmatrix}, \\
 & r \begin{bmatrix} A_3 & D_3 & C_3 \\ C_2 D_3^{\eta^*} & A_2 & 0 \\ D_2^{\eta^*} D_3^{\eta^*} & B_2^{\eta^*} & 0 \\ C_1 C_3^{\eta^*} & 0 & A_1 \\ D_1^{\eta^*} C_3^{\eta^*} & 0 & B_1^{\eta^*} \end{bmatrix} = r \begin{bmatrix} D_3 & C_3 \\ A_2 & 0 \\ B_2^{\eta^*} & 0 \\ 0 & A_1 \\ 0 & B_1^{\eta^*} \end{bmatrix}, \\
 & r \begin{bmatrix} A_3 & C_3 & D_3 C_2^{\eta^*} & D_3 D_2 \\ D_3^{\eta^*} & 0 & A_2^{\eta^*} & B_2 \\ C_1 C_3^{\eta^*} & A_1 & 0 & 0 \\ D_1^{\eta^*} C_3^{\eta^*} & B_1^{\eta^*} & 0 & 0 \end{bmatrix} = r \begin{bmatrix} C_3 \\ A_1 \\ B_1^{\eta^*} \end{bmatrix} + r \begin{bmatrix} D_3 \\ A_2 \\ B_2^{\eta^*} \end{bmatrix}.
 \end{aligned}$$

In this case the  $\eta$ -Hermitian reflexive solution of the system (I) can be expressed as the following

$$X = U \begin{pmatrix} X_1 & 0 \\ 0 & X_2 \end{pmatrix} U^{\eta^*} \in \mathbb{H}_r^{n \times n}(P)$$

where

$$\begin{aligned}
 X_1 = X_1^{\eta^*} &= E^+ F + F^{\eta^*} (E^+)^{\eta^*} - E^+ E F^{\eta^*} (E^+)^{\eta^*} + L_E K^+ Q (K^+)^{\eta^*} (L_E)^{\eta^*} \\
 &- L_E K^+ S W_2 (L_E K^+ S)^{\eta^*} - \frac{1}{2} L_E K^+ J M^+ Q [I + (S J^+)^{\eta^*}] (L_E K^+)^{\eta^*} \\
 &- \frac{1}{2} L_E K^+ (I + S J^+) Q (L_E K^+ J M^+)^{\eta^*} + L_E L_K V_1^{\eta^*} (L_E)^{\eta^*} + L_E V_1 (L_E L_K)^{\eta^*}, \quad (2)
 \end{aligned}$$

$$\begin{aligned}
 X_2 = X_2^{\eta^*} &= G^+ H + H^{\eta^*} (G^+)^{\eta^*} - G^+ G H^{\eta^*} (G^+)^{\eta^*} + \frac{1}{2} L_G M^+ Q (J^+)^{\eta^*} [I + (S^+ S)^{\eta^*}] (L_G)^{\eta^*} \\
 &+ \frac{1}{2} L_G (I + S^+ S) J^+ Q (L_G M^+)^{\eta^*} + L_G L_M W_2 (L_G L_M)^{\eta^*} + L_G L_M L_S W_1 (L_G)^{\eta^*} + \\
 &L_G W_1^{\eta^*} (L_G L_M L_S)^{\eta^*} + L_G L_J V_2^{\eta^*} (L_G)^{\eta^*} + L_G V_2 (L_G L_J)^{\eta^*}. \quad (3)
 \end{aligned}$$

where  $V_1, V_2, W_1$  and  $W_2 = W_2^{\eta^*}$  are arbitrary matrices over  $\mathbb{H}$  with appropriate sizes.

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