## Automorphisms of the Kronrod-Reeb graphs of Morse functions on 2-sphere

A. Kravchenko

(Taras Shevchenko National University of Kyiv, Ukraine) *E-mail:* annakravchenko1606@gmail.com

S. Maksymenko

(Institute of Mathematics, National Academy of Sciences of Ukraine, Kyiv, Ukraine) *E-mail:* maks@imath.kiev.ua

Let M be a compact two-dimensional manifold and ,  $f \in C^{\infty}(M, \mathbb{R})$  is Morse function and  $\Gamma_f$  its Kronrod-Reeb's graph. We denote the  $O(f) = \{f \circ h \mid h \in D(M)\}$  orbit of f with respect to the natural right action of the group of diffeomorphisms D(M) on  $C^{\infty}(M, \mathbb{R})$ , and  $S(f) = \{h \in D(M) \mid f \circ h = f\}$ is the stabilizer of this function. It is easy to show that each  $h \in S(f)$  induces an automorphism of the graph  $\Gamma_f$ . Let also  $S'(f) = S(f) \cap D_{id}(M)$  be a subgroup of  $D_{id}(M)$ , consisting of diffeomorphisms preserving f and isotopic to identical mappings and  $G_f$  be the group of automorphisms of the Kronrod-Reeb graph induced by diffeomorphisms belonging to S'(f). This group is the key ingredient for calculating the homotopy type of the orbit O(f).

In the previous article, the authors describe the structure of groups  $G_f$  for Morse functions on all orientational surfaces, except for sphere and torus. In this paper we study the case  $M = S^2$ . In this situation  $\Gamma_f$  is always a tree, and therefore all elements of the group  $G_f$  have a common fixed Fix(G<sub>f</sub>) subtree, which can be even from one point. The main result is to calculate the groups  $G_f$  for all Morse functions  $f: S^2 \to \mathbb{R}$  in which Fix(G<sub>f</sub>) is not the point.

**Theorem 1.** Let  $f \in C^{\infty}(S^2, \mathbb{R})$  be Morse function on a sphere. Suppose that all elements of the group  $G_f$  have a common fixed edge E. Let  $x \in E$  be an arbitrary point and A and B is the closure of the connected components  $S^2 \setminus p^{-1}(x)$ . Then A and B-double discs are invariant with respect to S'(f), the restriction of  $f|_A$ ,  $f|_B$  are Morse functions and we have the following isomorphism:

$$\phi: G_f \to G_{f|_A} \times G_{f|_B},$$

is determined by the formula  $\phi(\gamma) = (\gamma_{|\Gamma_A}; \gamma_{|\Gamma_B}).$ 

## References

- [1] E. A. Kudryavtseva. On the homotopy type of spaces of Morse functions on surfaces. Mat. Sb., 204(1):79-118, 2013.
- [2] E. A. Kudryavtseva. On the homotopy type of spaces of Morse functions on surfaces. Mat. Sb., 204(1):79-118, 2013.
- [3] S. Maksymenko and B. Feshchenko. Smooth functions on 2-torus whose Kronrod-Reeb graph contains a cycle. Methods Funct. Anal. Topology, 21(1):22-40, 2015.
- [4] S. Maksymenko and A. Kravchenko. Automorphisms of Kronrod-Reeb graphs of Morse functions on compact surfaces.2018.
- [5] S. Maksymenko. Deformations of functions on surfaces by isotopic to the identity diffeomorphisms. 2013.
- [6] Stephen Smale. Diffeomorphisms of the 2-sphere. Proc. Amer. Math. Soc., 10:621-626, 1959.