

Projective invariants of rational mappings

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We consider the k -jet spaces \mathbf{J}^k as k -jets of analytical mappings $\mathbb{C}P^1 \rightarrow \mathbb{C}P^1$ equipped with adjoint $\mathbb{P}\mathbf{SL}_2(\mathbb{C})$ -action:

$$f \mapsto A \circ f \circ A^{-1},$$

where $A \in \mathbb{P}\mathbf{SL}_2(\mathbb{C})$ (cf. [3]).

The representations of corresponding Lie algebras by vector fields on \mathbf{J}^0 is the following:

$$\langle \partial_z + \partial_u, z\partial_z + u\partial_u, z^2\partial_z + u^2\partial_u \rangle.$$

Theorem 1. (1) *The field of adjoint invariants ([1], [2]) is generated by differential invariants of the second and third orders*

$$J_2 = u_1^{-3} ((z - u)u_2 + 2u_1(u_1 + 1))^2,$$

$$J_3 = (z - u)^2 u_1^{-2} u_3 + 6(z - u)u_1^{-2}(u_1 + 1)u_2 + 6(u_1 + u_1^{-1}),$$

and invariant derivation

$$\nabla = \frac{(z - u)u_1u_2 + 2u_1^2(u_1 + 1)}{(z - u)(2u_1u_3 - 3u_2^2)} \frac{d}{dz}.$$

(2) *This field separates regular orbits.*

Equation $J_2(f) = 0$ has solutions of the form:

$$f(z) = \frac{ax + b}{cx + d}$$

where matrix

$$A = \begin{vmatrix} a & b \\ c & d \end{vmatrix}$$

has zero trace.

In general, values of invariant J_2 on linear fractional maps is equal to

$$J_2(f) = 4 \frac{(\text{tr} A)^2}{\det A},$$

and

$$J_3(f) = 6 \frac{\text{tr} A^2}{\det A} + 24.$$

We say that a rational mapping $f(z)$ is *singular* if $f(z)$ is linear fractional.

There exists an irreducible polynomial (we call it *generating polynomial*) $P_f(X, Y) \in \mathbb{C}[X, Y]$ such that $P_f(J_2(f), J_3(f)) = 0$ or in other words, the mapping f , as well as all mappings that are $\mathbb{P}\mathbf{SL}_2(\mathbb{C})$ -equivalent to f are solutions of the third order differential equation

$$P_f(J_2, J_3) = 0.$$

Theorem 2. (1) *Two regular rational mappings f and g are $\mathbb{P}\mathbf{SL}_2(\mathbb{C})$ -equivalent if and only if their adjoint generating polynomial are proportional.*

(2) *Orbit of a regular rational mapping f consists of the solution space of ordinary differential equation $P_f(J_2, J_3) = 0$.*

(1) For linear fractional transformations $f(z) = \frac{az+b}{cz+d}$, $ad - bc = 1$ we have $J_2(f) = 4(c+d)^2$ and therefore the corresponding differential equation has the following form:

$$u_1^{-3} ((z-u)u_2 + 2u_1(u_1+1))^2 - 4(a+d)^2 = 0$$

with 2-dimensional space of solutions.

(2) For the Jukowski mapping $f(z) = \frac{z^2+1}{2z}$ we have $P_f(X, Y) = -4X + 3Y - 45$ and therefore the corresponding differential equation has the following form

$$(z-u)^2 (3u_1u_3 - 4u_2^2) + 2(z-u)u_1(u_1+1)u_2 + u_1^2(2u_1-1)(u_1-2) = 0.$$

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