On 1-Harmonic Functions^{*}

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Received September 18, 2007, in final form December 17, 2007; Published online December 27, 2007 Original article is available at http://www.emis.de/journals/SIGMA/2007/127/

Abstract. Characterizations of entire subsolutions for the 1-harmonic equation of a constant 1-tension field are given with applications in geometry via transformation group theory. In particular, we prove that every level hypersurface of such a subsolution is calibrated and hence is area-minimizing over \mathbb{R} ; and every 7-dimensional $SO(2) \times SO(6)$ -invariant absolutely area-minimizing integral current in \mathbb{R}^8 is real analytic. The assumption on the $SO(2) \times SO(6)$ -invariance cannot be removed, due to the first counter-example in \mathbb{R}^8 , proved by Bombieri, De Girogi and Giusti.

Key words: 1-harmonic function; 1-tension field; absolutely area-minimizing integral current

2000 Mathematics Subject Classification: 53C40; 53C42

1 Introduction

The study of 1-harmonic functions, or more generally that of *p*-harmonic maps is an area of an active research that is related with many branches of mathematics. For instance, in a celebrated paper of Bombieri, De Girogi and Giusti [3], a 1-harmonic function has been constructed to provide a counter-example for interior regularity of the solution to the co-dimension one Plateau problem in \mathbb{R}^n for n > 7. Recall a C^1 functions $f : \mathbb{R}^n \to \mathbb{R}$ is said to be 1-harmonic if it is a weak solution of 1-harmonic equation

$$\operatorname{div}\left(\frac{\nabla f}{|\nabla f|}\right) = 0\,,\tag{1.1}$$

where $|\nabla f|$ is the length of the gradient ∇f of f, and for a C^2 function f without a critical point, div $\left(\frac{\nabla f}{|\nabla f|}\right)$ is said to be the 1-tension field of f.

In this paper, characterizations of entire subsolutions for the 1-harmonic equation of a constant 1-tension field are given in various aspects, and their relationships with calibration geometry are established (cf. Theorem 2, Corollary 3). As applications, we prove via transformation group theory (cf. [9, 10, 13, 2, 21]) that the cone over $S^1 \times S^5$ is not minimizing in \mathbb{R}^8 but is stable; that any 7-dimensional $SO(2) \times SO(6)$ -invariant absolutely area-minimizing integral current in \mathbb{R}^8 is real analytic; and that the only 7-dimensional $SO(3) \times SO(5)$ -invariant minimizing integral current with singularities in \mathbb{R}^8 is the cone over $S^2 \times S^4$, and is minimizing over \mathbb{R} (cf. Theorems 3–5). These results improved an early partial proof by numerical computation done by Plinio Simoes [17] in his Berkeley thesis. The assumption on the $SO(2) \times SO(6)$ -invariance cannot be removed, due to the first counter-example of Bombieri, De Girogi and Giusti that the cone over $S^3(\frac{1}{\sqrt{2}}) \times S^3(\frac{1}{\sqrt{2}}) \subset S^7(1)$ is area-minimizing in \mathbb{R}^8 . It should be pointed out that Fang-Hua Lin [14] proved that the cone over $S^1 \times S^5$ is one-sided area-minimizing and is stable by a different method. By constructing 1-harmonic functions on hyperbolic space H^n , $H^n \times H^n$,

^{*}This paper is a contribution to the Proceedings of the 2007 Midwest Geometry Conference in honor of Thomas P. Branson. The full collection is available at http://www.emis.de/journals/SIGMA/MGC2007.html

 $H^n \times SO(n, 1)$ and many other associated spaces, S.P. Wang and the author [19] show the Bernstein Conjecture in these spaces to be false in all dimensions. In particular, these constructions give the *first* set of examples of complete, smooth, embedded, minimal (hyper-)surfaces in hyperbolic space H^n in all dimensions (cf. also Remark 3(ii)).

2 Fundamentals in geometric measure theory

For our subsequent development, we recall some fundamental facts, definitions, and notations, for which the reference is Federer's book [5] and paper [7].

Let N denote an n-dimensional Riemannian manifold and denote by $\mathcal{R}_p^{\text{loc}}(N)$ the set of pdimensional, locally rectifiable currents (of Federer and Fleming, cf. [8]) on N. For $S \in \mathcal{R}_p^{\text{loc}}(N)$, denote the mass of S by $\mathbf{M}(S)$, and the *boundary* of S by ∂S , and is given by $(\partial S)(w) = S(dw)$, where w is a smooth p-form and d is the exterior differentiation. From a calculus of variational viewpoint, we make the following

Definition 1. A current $T \in \mathcal{R}_k^{\text{loc}}(N)$ is said to be *stationary* if $\frac{d}{dt}\mathbf{M}(\phi_{t_*}^V(T))|_{t=0}$ for all vector fields V on N with compact support where ϕ_t^V is the flow associated with V, and *stable* if for every vector fields V on N with compact support, there exists an $\epsilon > 0$ such that $\mathbf{M}(T) \leq \mathbf{M}(\phi_{t_*}^V(T))$ for $|t| < \epsilon$.

We are primarily interested in minimizing currents.

Definition 2. A current $T \in \mathcal{R}_k^{\text{loc}}(N)$ is homologically (resp. absolutely) area-minimizing over \mathbb{Z} if for all compact sets $K \subset M$, we have $\mathbf{M}(\phi_K T) \leq \mathbf{M}((\phi_K T) + S)$ for all $S \in \mathcal{R}_k^{\text{loc}}(N)$ having compact support and being the boundary of some current in $\mathcal{R}_{k+1}^{\text{loc}}(N)$ with compact support (resp. the empty boundary)(here ϕ_K denotes the characteristic function on K).

Using a dimension reduction technique, Federer proves that the support of an area-minimizing integral current T [8] minus another compact set S whose Hausdorff dimension does not exceed n-8 is an (n-1)-dimensional analytic manifold [6]. Hence, if $n \leq 7$, then $S = \emptyset$. If n = 8, S consists of at most isolated points [5, 5.4.16]. This result is optimal by the counter-example due to Bombieri–De Giorgi–Giusti [3] that $\{x \in \mathbb{R}^{2m} : x_1^2 + \cdots + x_m^2 = x_{m+1}^2 + \cdots + x_{2m}^2\}$ is an area-minimizing cone over the product of (m-1)-spheres $\{x \in \mathbb{R}^{2m} : x_1^2 + \cdots + x_m^2 = x_{m+1}^2 + \cdots + x_{2m}^2 = \frac{1}{2}\}$ in \mathbb{R}^{2m} for $m \geq 4$.

The union of the groups $\mathcal{F}_{m,K}(U) = \{R + \partial T : R \in \mathcal{R}_{m,K}(U), T \in \mathcal{R}_{m+1,K}(U)\}$ corresponding to all compact $K \subset U$ is the group $\mathcal{F}_m(U)$ of *m*-dimensional integral flat chains in an open subset U of \mathbb{R}^n . We denote the group of *m*-dimensional integral flat chains, cycles and boundaries by $\mathcal{F}_m(A) = \mathcal{F}_m(\mathbb{R}^n) \cap \{S : \operatorname{spt} S \subset A\}, \mathcal{Z}_m(A, B) = \mathcal{F}_m(A) \cap \{S : \partial S \subset \mathcal{F}_m(B) \text{ or } m = 0\}$, and $\mathcal{B}_m(A, B) = \{R + \partial T : R \in \mathcal{F}_m(B), T \in \mathcal{F}_{m+1}(A)\}$ respectively. Similarly, we define and denote $\mathbf{F}_m(A), \mathbf{Z}_m(A, B)$ and $\mathbf{B}_m(A, B)$ the vector space of *m*-dimensional real flat chains, cycles and boundaries respectively, where $B \subset A$ are compact Lipschitz neighborhood retract in U.

For every positive convex parametric integrand ψ , and every compact subset K of A, we define $\mathcal{Z}_{m,K}(A, B) = \mathcal{Z}_m(A, B) \cap \{R : \operatorname{spt} R \subset K\}, \mathcal{B}_{m,K}(A, B) = \mathcal{B}_m(A, B) \cap \{R : \operatorname{spt} R \subset K\}, \mathbf{Z}_{m,K}(A, B) = \mathbf{Z}_m(A, B) \cap \{R : \operatorname{spt} R \subset K\}, \text{ and } \mathbf{B}_{m,K}(A, B) = \mathbf{B}_m(A, B) \cap \{R : \operatorname{spt} R \subset K\},$ and make the following

Definition 3. An *m*-dimensional rectifiable current Q (resp. Q') is said to be absolutely (resp. homologically) ψ -minimizing in K with respect to (A, B) over \mathbb{Z} if

$$\int_{Q} \psi = \inf \left\{ \int_{S} \psi : S \in \mathcal{F}_{m,K}(U), Q - S \in \mathcal{Z}_{m,K}(A,B) \right\}$$

(resp.
$$\int_{Q'} \psi = \inf \left\{ \int_{S} \psi : S \in \mathcal{B}_{m,K}(U), Q' - S \in \mathcal{B}_{m,K}(A,B) \right\}).$$

Definition 4. An *m*-dimensional real flat chain Q (resp. Q') is said to be *absolutely (resp.* homologically) ψ -minimizing in K with respect to (A, B) over \mathbb{R} if

$$\int_{Q} \psi = \inf \left\{ \int_{S} \psi : S \in \mathbf{F}_{m,K}(U), Q - S \in \mathbf{Z}_{m,K}(A,B) \right\}$$

(resp.
$$\int_{Q'} \psi = \inf \left\{ \int_{S} \psi : S \in \mathbf{B}_{m,K}(U), Q' - S \in \mathbf{B}_{m,K}(A,B) \right\}$$
).

We will make comparisons between real and integral absolute (resp. homological) minimizing currents in the subsequent Sections 3, 4, and 5.

3 Characterizations of subsolutions for 1-harmonic equation of constant 1-tension field

We connect an entire subsolution of this sort, with a calibration. Recall a calibration is a closed form with comass 1.

Lemma 1. Let M be a complete noncompact Riemannian manifold. For any $x_0 \in M$ and any pair of positive numbers s, t with s < t, there exists a rotationally symmetric Lipschitz continuous function $\psi(x) = \psi(x; s, t)$ and a constant $C_1 > 0$ (independent of x_0, s, t) with the properties:

(i)
$$\psi \equiv 1$$
 on $B(x_0; s)$, and $\psi \equiv 0$ off $B(x_0; t)$;
(ii) $|\nabla \psi| \le \frac{C_1}{t-s}$, a.e. on M .
(3.1)

Proof. (cf. Andreotti and Vesentini [1], Yau [22], Karp [11]).

Theorem 1. Let Ω be a domain in \mathbb{R}^n containing a ball $B(x_0, r)$ of radius r, centered at x_0 , and $g: \Omega \to \mathbb{R}$ be a continuous function with $g \ge 0$, and $c = \inf_{x \in B(x_0, \frac{r}{2})} g(x)$. Let $f: \Omega \to \mathbb{R}$ be

 $a C^1$ weak solution of

$$\operatorname{div}\left(\frac{\nabla f}{|\nabla f|}\right) = g(x) \qquad on \ \Omega, \tag{3.2}$$

then the infimum c satisfies

$$0 \le c \le \frac{C_1 2^n}{r},$$

where C_1 is as in (3.1).

Proof. Let $\psi \ge 0$ be as in Lemma 1, in which $M = \mathbb{R}^n$, t = r, $s = \frac{r}{2}$. Choose ψ to be a test function in the distribution sense of (3.2). Then via the assumption on g, and Cauchy–Schwarz inequality we have:

$$\begin{split} \int_{B(x_0,\frac{r}{2})} c\psi(x)dx &\leq \int_{B(x_0,\frac{r}{2})} g(x)\psi(x)dx \\ &\leq \int_{B(x_0,r)} g(x)\psi(x)dx = -\int_{B(x_0,r)} \frac{\nabla f}{|\nabla f|} \cdot \nabla \psi dx \leq \int_{B(x_0,r)} |\nabla \psi| dx. \end{split}$$

Hence,

$$c\operatorname{Vol}\left(B\left(x_{0}, \frac{r}{2}\right)\right) \leq \frac{C_{1}}{r}\operatorname{Vol}(B(x_{0}, r))$$

yields the desired.

Corollary 1. Let $f : \mathbb{R}^n \to \mathbb{R}$ be a C^1 weak subsolution of 1-harmonic equation (1.1) with constant 1-tension field c, i.e. $0 \leq \operatorname{div}\left(\frac{\nabla f}{|\nabla f|}\right) = c$ in the distribution sense. Then f is a 1-harmonic function.

Corollary 2. There does not exist a C^1 weak subsolution $f : \mathbb{R}^n \to \mathbb{R}$ of equation (3.2) with $\lim_{r\to\infty} \inf_{x\in B(x_0,r)} g(x) > 0$, for any $x_0 \in \mathbb{R}^n$.

Let $A \subset \mathbb{R}^n$ be an open set. We denote $BV_{\text{loc}}(A) = \{f \in L^1_{\text{loc}}(A): \text{ the distributional derivatives } D_i f$ of f are (locally) measures} = $\{f \in L^1_{\text{loc}}(A): \text{ supp } \phi_n \subset K \subset A, \phi_n \to 0$ uniformly, imply $\left(\frac{\partial}{\partial x_i}f\right)\phi_n \to 0$ }. Let $Df = (D_1f, \ldots, D_nf)$ denote the gradient of f in the sense of distributions and |Df| the scalar measure defined by $\int_K |Df| = \sup \int_K \sum_i \epsilon_i(x)D_i f$, where the supremum is taken over all sets $\{\epsilon_i(x), i = 1, \ldots, n\}$ of $C^{\infty}(K)$ functions which satisfy $\sum \epsilon_i^2(x) \leq 1$.

Definition 5. A function $f \in BV_{loc}(A)$ has least gradient in A if for every $g \in BV_{loc}(A)$, with compact support $K \subset A$ we have

$$\int_{K} |Df| \le \int_{K} |D(f+g)|. \tag{3.3}$$

Definition 6. Let E be a set in \mathbb{R}^n and ϕ_E its characteristic function. E has an oriented boundary of least area with respect to A, if (i) $\phi_E \in BV_{\text{loc}}(A)$ and (ii) for each $g \in BV_{\text{loc}}(A)$ with compact support $K \subset A$ we have $\int_K |D\phi_E| \leq \int_K |D(\phi_E + g)|$.

Theorem 2. Let $f \in H^{1,1}_{loc}(\mathbb{R}^n)$, and $\nabla f(x) \neq 0$ for every x in \mathbb{R}^n . Let $E_{\lambda} = \{x : f(x) \geq \lambda\}$, and $S_{\lambda} = \{x : f(x) = \lambda\}$. We denote the set of integers by \mathbb{Z} . Then the following thirteen statements (1)–(13) are equivalent and each of them implies the fourteenth statement (14).

- 1. $f: \mathbb{R}^n \to \mathbb{R}$ is a C^1 weak subsolution of (1.1) with constant 1-tension field.
- 2. f is a C^1 weak solution of (1.1) on \mathbb{R}^n .
- 3. f is a C^1 1-harmonic function on \mathbb{R}^n .
- 4. For each $(a, t_0) = (a_1, \ldots, a_{n-1}, t_0) \in S_{\lambda}$, there exists a neighborhood \mathcal{D} of a in \mathbb{R}^{n-1} , and a unique real analytic function $\eta : \mathcal{D} \to \mathbb{R}$ such that $\eta(a) = t_0$, $f(x_1, \ldots, x_{n-1}, \eta(x_1, \ldots, x_{n-1})) = \lambda$ and div $\left(\frac{\nabla \eta}{\sqrt{1+|\nabla \eta|^2}}\right) = 0$ on \mathcal{D} .
- 5. Each level hypersurface S_{λ} is minimal in \mathbb{R}^n .
- 6. $\frac{*df}{|df|}$ is a globally defined "weakly" closed form with comass 1.
- 7. f is a function of least gradient in \mathbb{R}^n .
- 8. Each E_{λ} , $\lambda \in \mathbb{R}$ has an oriented boundary of least area with respect to \mathbb{R}^n .
- 9. Each level hypersurface S_{λ} is absolutely area-minimizing in \mathbb{R}^n over \mathbb{Z} .
- 10. Each level hypersurface S_{λ} is absolutely area-minimizing in \mathbb{R}^n over \mathbb{R} .
- 11. Each level hypersurface S_{λ} is homologically area-minimizing in \mathbb{R}^n over \mathbb{R} .
- 12. Each level hypersurface S_{λ} is homologically area-minimizing in \mathbb{R}^n over \mathbb{Z} .
- 13. Each level hypersurface S_{λ} is stable in \mathbb{R}^n .
- 14. If $f \in C^2(\mathbb{R}^n)$, then $\frac{*df}{|df|}$ is closed and the restriction $\frac{*df}{|df|}\Big|_{S_{\lambda}}$ is its volume form, hence each S_{λ} is real absolutely area-minimizing in \mathbb{R}^n over \mathbb{R} .

1

Corollary 3. Every level hypersurface of a C^2 subsolution of 1-harmonic equation on \mathbb{R}^{n+1} with constant 1-tension field is calibrated and hence is area-minimizing over \mathbb{R} .

Proof. (1) \Leftrightarrow (2) \Leftrightarrow (3) : This follows immediately from Corollary 1.

 $(2) \Leftrightarrow (4)$: (\Rightarrow) Let $f(x_1, \ldots, x_{n-1}, t) = \eta(x_1, \ldots, x_{n-1}) - t$. The assertion follows from the implicit function theorem and

$$0 = \int \frac{\sum_{i=1}^{n-1} \frac{\partial f}{\partial x_i} \frac{\partial \varphi}{\partial x_i}}{|\nabla f|} + \int \frac{\frac{\partial f}{\partial t}}{|\nabla f|} \frac{\partial \varphi}{\partial t} = \int \sum_{i=1}^{n-1} \frac{\frac{\partial \eta}{\partial x_i}}{\sqrt{1+|\nabla \eta|^2}} \frac{\partial \varphi}{\partial x_i}$$
(3.4)

for all $\varphi \in C_0^{\infty}(\mathcal{D} \times \mathbb{R})$. The regularity of solutions of minimal surface equation implies that η is real analytic and completes the proof. (\Leftarrow) This follows immediately from (3.3).

 $(4) \Leftrightarrow (5)$: This is due to the fact that the graph of a solution to the minimal surface equation on \mathcal{D} is a minimal hypersurface in $\mathcal{D} \times \mathbb{R}$.

(2) \Leftrightarrow (6) : This follows from the following: For every $\phi \in C_0^{\infty}(A)$,

$$\int_{A} \frac{*df}{|df|} \wedge d\phi = \int_{A} \sum_{i,j=1}^{n} (-1)^{i-1} \frac{\frac{\partial f}{\partial x_i}}{|\nabla f|} dx^1 \wedge \dots \wedge dx^{i-1} \wedge dx^{i+1} \wedge \dots \wedge dx^n \wedge \frac{\partial \phi}{\partial x_j} dx^j$$
$$= \int_{A} \sum_{i=1}^{n} (-1)^{n-1} \frac{\frac{\partial f}{\partial x_i}}{|\nabla f|} dx^1 \wedge \dots \wedge dx^i \wedge \dots \wedge dx^n.$$

(2) \Rightarrow (7): let us first assume that $g \in C_0^1(A)$. Let $h(t) = \int |D(f+tg)|$. Then

$$h'(t) = \int \frac{\left(\sum_{i=1}^{n} \frac{\partial (f+tg)}{\partial x_i} \frac{\partial g}{\partial x_i}\right)}{\left(\sum_{i=1}^{n} \left(\frac{\partial (f+tg)}{\partial x_i}\right)^2\right)^{\frac{1}{2}}}.$$

Hence h'(0) = 0 by assumption. Furthermore,

$$h''(t) = \int \frac{\left(\sum_{i=1}^{n} \left(\frac{\partial g}{\partial x_{i}}\right)^{2}\right) \left(\sum_{i=1}^{n} \left(\frac{\partial (f+tg)}{\partial x_{i}}\right)^{2}\right) - \left(\sum_{i=1}^{n} \frac{\partial (f+tg)}{\partial x_{i}} \frac{\partial g}{\partial x_{i}}\right)^{2}}{\left[\sum_{i=1}^{n} \left(\frac{\partial (f+tg)}{\partial x_{i}}\right)^{2}\right]^{\frac{3}{2}}} \ge 0,$$

by the Cauchy–Schwarz inequality. Therefore $\int |Df| = h(0) \leq h(1) = \int |D(f+g)|$. If $g \in$ $BV_{loc}(A)$ with compact support K and let $Dg = G_1 + G_2$ where G_1 is completely continuous and G_2 is the singular part of Dg with support N_g of measure zero. Then we have $\int_K |D(f +$ $g)| = \int_{K} |Df + G_1| + \int_{K} |G_2| \text{ because } f \in H^{1,1}_{\text{loc}}(A). \text{ Let } g_{\varepsilon} = g * \psi_{\varepsilon} \text{ where } \psi_{\varepsilon} \text{ is a mollifier.}$ Then $g \in C^1_0(A)$ and $\int_{K_{\epsilon}} |Df| \leq \int_{K_{\epsilon}} |D(f + g_{\epsilon})| \leq \int_{K_{\epsilon}} |Df + G_1 * \Psi_{\epsilon}| + \int_A |G_2 * \Psi_{\epsilon}|, \text{ where } U_{\varepsilon} = g + \psi_{\varepsilon} \text{ where } \psi_{\varepsilon} \text{ is a mollifier.}$ $K_{\epsilon} = \{x \in A : \operatorname{dist}(x, K) < \epsilon\}$. Letting $\epsilon \to 0$ completes the proof (cf. [3]).

(7) \Rightarrow (8) : This follows from Coarea formula for BV functions [15], $\int_K |Df| = \int_{-\infty}^{\infty} (\int_K |D\phi_\lambda|) d\lambda$ together with two observations:

(i) If f_1 and f_2 satisfy (3.3), so does $\sup(f_1, f_2)$.

(ii) If $f_i \in BV_{\text{loc}}(A), f_i \to f$ in L^1_{loc} and each f_i satisfies (3.3), so does also $f \in BV_{\text{loc}}(A)$ and satisfies (3.3).

For detailed proof see [16].

 $(8) \Rightarrow (9)$: Let $\phi_{\lambda} = \phi_{E_{\lambda}}$. Since for every x in \mathbb{R}^n , $\nabla f(x) \neq 0$, $\partial E_{\lambda} = S_{\lambda}$ for $S_{\lambda} \neq \emptyset$. It follows from a theorem of Miranda [15] that on any compact set K in \mathbb{R}^n , the Hausdorff (n-1)-measure

$$\mathcal{H}^{n-1}(K \cap S_{\lambda}) = \int_{K} |D\phi_{\lambda}| \le \int_{K} |D(\phi_{\lambda} + g)| = \mathcal{H}^{n-1}(K \cap T)$$

for all sets T with $\partial(K \cap T) = \partial(K \cap S_{\lambda})$.

 $(9) \Rightarrow (10)$: It follows from Theorem 6.

 $(10) \Rightarrow (11) \Rightarrow (12)$: Since absolute area-minimization over $\mathbb{R} \Rightarrow$ homological area-minimization over $\mathbb{R} \Rightarrow$ homological area-minimization over \mathbb{Z} .

 $(12) \Rightarrow (13) \Rightarrow (5)$: Since homological minimization over $\mathbb{Z} \Rightarrow$ stability \Rightarrow minimality. This completes the proof of $(1) \Leftrightarrow \cdots \Leftrightarrow (13)$.

 $(2) \Rightarrow (14)$: If $f \in C^2(A)$ then by $(3.4) \frac{*df}{|df|}$ is closed. Now let e_1, \ldots, e_{n-1} be an orthonormal basis for the tangent space of S_{λ} at x_0 and ν a unit normal vector at x_0 . We denote by tilde " \sim " the canonical isomorphism between a tangent space and its dual space. To show $\frac{*df}{|df|}$ has comass 1, note for any (n-1)-vector field ξ ,

$$\frac{*df}{|df|}(\xi) = \left(*\frac{\nabla f}{|\nabla f|}\right)(\xi) \quad \left(\text{because } \frac{df}{|df|}(X) = \frac{Xf}{|\nabla f|} = \left\langle\frac{\nabla f}{|\nabla f|}, X\right\rangle\right)$$
$$= (*\tilde{\nu})(\xi) = (e_1 \wedge \cdots \wedge e_{n-1})(\xi) = \langle e_1 \wedge \cdots \wedge e_{n-1}, \xi \rangle.$$

In particular $\frac{*df}{|df|}(e_1 \wedge \cdots \wedge e_{n-1}) = 1$, $\frac{*df}{|df|}(\xi) \leq 1$ and $\frac{*df}{|df|}\Big|_{S_{\lambda}}$ = volume element of S_{λ} . By the formalism of Stokes theorem, for any integral current T with $\partial T = \partial(S_{\lambda} \cap B_r)$

$$M(S_{\lambda} \cap B_r) = (S_{\lambda} \cap B_r) \left(\frac{*df}{|df|}\right) = T\left(\frac{*df}{|df|}\right)$$
$$= \int \frac{*df}{|df|} \left(\overrightarrow{T_x}\right) d||T||(x) \le \int d||T|| = M(T),$$

where \overrightarrow{T} is the field of oriented unit tangent planes to T.

Remark 1. In Theorem 2, if one replace \mathbb{R}^n with an open subset A in \mathbb{R}^n , then assertions $(2) \Leftrightarrow \cdots \Leftrightarrow (13) \Rightarrow (14)$ remain to be true.

Remark 2. Concerning the assertion $(2) \Rightarrow (7)$, a stronger theorem can be found in [3]: Let $A \subset \mathbb{R}^n$ be an open set and let $f \in H^{1,1}_{\text{loc}}(A)$. Suppose that (i) $\mathcal{H}_n(\{x \in A : |\nabla f| = 0\}) = 0$, (ii) $\mathcal{H}_{n-1}(N) = 0$ where N is a closet set in A, (iii) $\int_{A-N} |\nabla f|^{-1} \sum_{i=1}^n \frac{\partial f}{\partial x_i} \frac{\partial \phi}{\partial x_i} dx = 0$ for every $\phi \in C^1_0(A-N)$. Then f has least gradient with respect to A.

Remark 3. (i) The assertion $(7) \Rightarrow (9)$ is due to Miranda.

(ii) Connecting the assertions (5), (6), and (12) on Riemannian manifolds, S.P. Wang and the author [19] prove that if each level hypersurface of a smooth function $f: M \to \mathbb{R}$ on an oriented *Riemannian manifold* M with nowhere vanishing ∇f , is minimal, then there exists a closed form with comass 1 on M and hence each level hypersurface is homologically area-minimizing over \mathbb{R} .

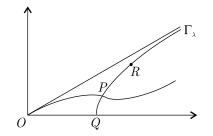
Corollary 4. Let A be an open subset in \mathbb{R}^n , N be a closed subset in A with $\mathcal{H}_{n-1}(N) = 0$. Then the graph of any weak solution of the minimal surface equation $\sum_{i=1}^n \frac{\partial}{\partial x_i} \left(\frac{\frac{\partial f}{\partial x_i}}{\sqrt{1+|\nabla f|^2}} \right) = 0$ on A - N is in fact absolutely area-minimizing in $A \times \mathbb{R} \subset \mathbb{R}^{n+1}$ over \mathbb{R} . **Proof.** Applying (3.4) in which " $f(x_1, \ldots, x_{n-1}, t) = \eta(x_1, \ldots, x_{n-1}) - t$ " is replaced with " $F(x_1, \ldots, x_n, t) = f(x_1, \ldots, x_n) - t$ ", and Remark 2, we have that F is a C^1 1-harmonic function in A. By Theorem 2, the zero level set $S_0 = \{(x_1, \ldots, x_n, t) : t = f(x_1, \ldots, x_n)\}$ is absolutely area-minimizing in $A \times \mathbb{R} \subset \mathbb{R}^{n+1}$ over \mathbb{R} .

4 Further applications

A natural question arises: Are Bombieri–De Giorgi–Giusti and Lawson cones the only $SO(m) \times SO(n)$ -invariant singular absolutely area-minimizing integral currents in Euclidean space \mathbb{R}^{m+n+2} ? The answer is affirmative. Combining the theory of 1-harmonic functions developed, and the techniques of transformation groups in [10, 13, 2], and [21], evolved from the ideas in [9], one obtains the following:

Theorem 3. The cone $C(S^m \times S^n)$ over $S^m \times S^n$ is the unique singular absolutely areaminimizing hypersurface in the class of $SO(m + 1) \times SO(n + 1)$ -invariant integral currents in \mathbb{R}^{m+n+2} over \mathbb{R} for m + n > 7 or m + n = 6, $|m - n| \leq 2$. (It is known that the cone is not even stable otherwise.)

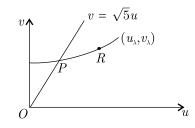
Proof. Assume m = n. Let Lie group $G = SO(n+1) \times SO(n+1)$ acting on manifold $\mathbb{R}^{n+1} \times \mathbb{R}^{n+1}$ in the standard way, i.e. assigning $((A, B), (x, y)) \in G \times \mathbb{R}^{2n+2}$ to $(A \cdot x, B \cdot y) \in G$ \mathbb{R}^{2n+2} , where "." is the matrix multiplication. Then the collection X of principle orbits is given by $X = \{(x,y) \in \mathbb{R}^{2n+2} : |x||y| \neq 0\}$, where " $|\cdot|$ " is the length of " \cdot " in \mathbb{R}^{n+1} . The orbit space which is stratified, can be represented as $\mathbb{R}^{2n+2}/G = \{(u,v) \in \mathbb{R}^2 : u, v \geq 0\} =$ $X \cup \{(u,v) \in \mathbb{R}^2 : u = 0, v > 0\} \cup \{(u,v) \in \mathbb{R}^2 : u > 0, v = 0\} \cup \{(0,0)\}.$ The canonical metric on \mathbb{R}^{2n+2}/G (compatible with the fibration over each stratum) is the usual flat one $ds_0^2 = du^2 + dv^2$. The canonical projection $\pi : \mathbb{R}^{2n+2} \to \mathbb{R}^{2n+2}/G$ is given by $\pi(x,y) = (|x|,|y|)$, and let $X/G = \pi(X)$. Then the length of a curve σ in $(X/G, ds_0^2)$ is the length of any orthogonal trajectory through the corresponding orbits in X, and 2n-dimensional volume of $\pi^{-1}((u, v))$ (which is diffeomorphic to $S^n \times S^n$) is proportional to $u^n v^n$, for $(u, v) \in X/G$. Thus if we choose the metric $ds^2 = u^{2n}v^{2n}(du^2 + dv^2)$ on \mathbb{R}^{2n+2}/G , then by Fubini's theorem, the length of a curve σ in $(\mathbb{R}^{2n+2}/G, ds^2)$ is equal to (2n+1)-dimensional volume of hypersurface $\pi^{-1}\sigma$ (with possible singularities) in \mathbb{R}^{2n+2} , up to a constant factor. It follows that σ is a length minimizing geodesic "downstairs" (in $(\mathbb{R}^{2n+2}/G, ds^2)$), if and only if $\pi^{-1}\sigma$ is area-minimizing in the class of G-invariant (2n+1)-dimensional currents "upstairs" (in $(\mathbb{R}^{2n+2}, dx_1^2 + \cdots + dx_{2n+2}^2))$, or equivalently, $\pi^{-1}\sigma$ is area-minimizing in $(\mathbb{R}^{2n+2}, dx_1^2 + \cdots + dx_{2n+2}^2)$ in general (cf. [13], [2, p. 174, 6.4] and [21]). Furthermore, if a length minimizing geodesic σ meets the boundary $\{(u,v)\in\mathbb{R}^2: u=0, v>0\}\cup\{(u,v)\in\mathbb{R}^2: u>0, v=0\}$, it meets the boundary orthogonally by the first variational formula for the arc-length functional, and the corresponding $\pi^{-1}\sigma$ is a regular, embedded and analytic hypersurface in \mathbb{R}^{2n+2} . If σ meets the vertex $\{(0,0)\}$, then $\pi^{-1}\sigma$ is singular. Therefore, it suffices to show that any curve in \mathbb{R}^{2n+2}/G , other than the diagonal ray emanating from the origin is not absolutely length minimizing with respect to the metric $ds^2 = u^{2n}v^{2n}(du^2 + dv^2).$



Now let $\Gamma = \{(u_0(t), v_0(t))\}$ be the geodesic through (1, 0) in $(\mathbb{R}^{2n+2}/G, ds^2)$, and $\Gamma_{\lambda} = \{(\lambda u_0(t), \lambda v_0(t))\}, \lambda > 0$. In [3], a 1-harmonic function was constructed in such a way that the lift of family $\{\Gamma_{\lambda}\}$ of these homothetic geodesics are level hypersurfaces in $(\mathbb{R}^{2n+2}, dx_1^2 + \cdots + dx_{2n+2}^2)$. Hence Γ_{λ} is absolutely length minimizing in $(\mathbb{R}^{2n+2}/G, ds^2)$ (cf. also Theorem 2, Remark 2). Now suppose Theorem 3 were not true. Then there would exist a curve $QP \subset \Gamma_{\lambda}$ transverse to a length minimizing curve OP. It follows that the length l(OP) of OP would satisfy l(OP) = l(QP). Consider the curve OPR where R is on the curve Γ_{λ} , and l(OPR) = l(QPR). Then the curve OPR would be a geodesic, and hence smooth at P. This is a contradiction. Similarly, one can show the remaining case $m \neq n$.

Theorem 4. The cone $C(S^1 \times S^5)$ over $S^1 \times S^5$ is not absolutely area-minimizing, although it is stable.

Proof. Suppose, on the contrary, that the cone were absolutely area-minimizing. Then consider Lie group $G = SO(2) \times SO(6)$ acting on manifold $\mathbb{R}^2 \times \mathbb{R}^6$ in the standard way. By the previous argument, this would imply the line segment \overline{OP} were length-minimizing in $(\mathbb{R}^8/G, ds^2)$, where $ds^2 = u^2 v^6 (du^2 + dv^2)$. On the other hand, based on the study of Simoes' thesis [17], [13] and [21], the level curve (u_λ, v_λ) in the u, v-plane is absolutely length-minimizing. Argue as before, the curve OPR would be smooth at P. This is a contradiction. The stability of the cone follows from Simons' work [18].



Theorem 5. Any 7-dimensional $SO(2) \times SO(6)$ -invariant absolutely area- minimizing integral current in \mathbb{R}^8 is real analytic.

Proof. By the argument given in the proof of Theorem 3, it suffices to show that any curve in \mathbb{R}^{2n+2}/G , from the origin is not absolutely length minimizing with respect to the metric $ds^2 = u^2v^6(du^2 + dv^2)$. By Theorem 4, the diagonal ray emanating from the origin is not length minimizing. Similarly, if there were an absolutely length minimizing curve starting from the origin lying above $v = \sqrt{5}u$, then this would lead to an irregularity of a geodesic, a contradiction.

5 Comparison theorem

It is known that each level hypersurface of a function of least gradient defined on an open subset $A \subset \mathbb{R}^n$ is absolutely area-minimizing in A over \mathbb{Z} . It is tempting to ask it if is absolutely area-minimizing in A over \mathbb{R} . This motivates our discussion on comparison between real and integral absolute (or homological) minima. In general they are distinct. Examples are given by Almgren [7, 5.11], Federer [7] and Lawson [12]. Furthermore, in the case of 1-dimensional (or co-dimension 1) integral flat chains, Federer [7] has shown that real and integral homological (or absolute) minimizing are the same.

Let \overline{M} be a locally Lipschitz neighborhood retract in \mathbb{R}^n (i.e. there exists a locally Lipschitz map which retracts a neighborhood of \overline{M} onto \overline{M}), M be an open subset of \overline{M} , and A be an open subset of \mathbb{R}^n . Using the assumption on vanishing topology, an exhaustion of M by an increasing sequence of compact set $K_i \subset M$, we obtain the following: **Theorem 6.** (1) Let T^{n-1} denote a codimension 1 integral absolutely area-minimizing rectifiable current in M with homology group $H_{n-1}(\overline{M}) = 0$. Then T^{n-1} is absolutely area-minimizing in Mif and only if T^{n-1} is absolutely area-minimizing in A; and if and only if T^{n-1} is real absolutely area-minimizing in A. (2) Let $H_1(\overline{M}) = 0$. T^1 is a homologically area-minimizing rectifiable current of degree 1 of M if and only if T^1 is real homologically area-minimizing in M.

We have the following immediate

Corollary 5. The level hypersurface of a function of least gradient in an open subset A of \mathbb{R}^n is absolutely area-minimizing over \mathbb{R} .

Corollary 6. Let N be a closed set in $A \subset \mathbb{R}^n$ with $H_{n-1}(N) = 0$. The graph of any weak solution of the minimal surface equation $\sum_{i=1}^n \frac{\partial}{\partial x_i} \left(\frac{\frac{\partial f}{\partial x_i}}{\sqrt{1+|\nabla f|^2}} \right) = 0$ on A - N is in fact absolutely area-minimizing in $A \times \mathbb{R} \subset \mathbb{R}^{N+1}$ over \mathbb{R} .

Corollary 7. All the examples we find in [21] are absolutely area-minimizing over \mathbb{R} .

Acknowledgements

Research was partially supported by NSF Award No DMS-0508661, OU Presidential International Travel Fellowship, and OU Faculty Enrichment Grant. The author wishes to thank Professors H. Blaine Lawson Jr., and Wu-Yi Hsiang for their interest, and Professor Herbert Federer for his help in Theorem 6 which essentially derives from him. The author also wishes to express his gratitude to the referees and the editors for their comments and suggestions without which the present form of this article would not be possible.

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