

EXISTENCE OF A CONTINUOUSLY DIFFERENTIABLE SOLUTION OF A CAUCHY PROBLEM FOR A SYSTEM OF INTEGRO-FUNCTIONAL EQUATIONS WITH PARTIAL DERIVATIVES AND LINEARLY TRANSFORMED ARGUMENTS

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A theorem of existence of continuously differentiable solution of a system of integro-functional equations with partial derivatives and linearly transformed arguments is proved.

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We consider a system of nonlinear differential equations

$$u_t - \Lambda u_x = f(t, x, u(x, t), u(\lambda t, x), u(\lambda t, \mu x)),$$

$$\int_0^{h(t,x)} \psi(t, x, s, u(s, x), u(\lambda s, x), u(\lambda s, \mu x)) ds), \tag{1}$$

where $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_n)$, $\lambda_i, i = \overline{1, n}$, are real numbers, $\lambda, \mu \in \mathbb{R}$ ($\lambda\mu \neq 0$), t, x belong to some closed domain \overline{D} , $f(t, x, v_1, v_2, v_3, v_4) : \overline{D} \times \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^1 \rightarrow \mathbb{R}^n$, where

$$v_4 = \int_0^{h(t,x)} \psi(t, x, s, u(s, x), u(\lambda s, x), u(\lambda s, \mu x)) ds,$$

$u(t, x)$ is an unknown vector-valued function.

Denote by $\lambda_* = \min_{1 \leq i \leq n} \lambda_i$, $\lambda^* = \max_{1 \leq i \leq n} \lambda_i$, and assume that the domain \overline{D} is bounded by a segment $[0, a]$ on the axis OX ($a = \text{const} > 0$) and characteristics l_1 and l_2 , with angular coefficients $1/\lambda^*$ and $1/\lambda_*$, starting in the points 0 and a , respectively.

The aim of this article is to study the problem of existence of a solution of the system such that the solution has a continuous derivative of the first order in \overline{D} . Also, this solution should satisfy the initial condition

$$u_i(0, x) = \varphi_i(x), \tag{2}$$

where $\varphi(x)$ is a vector-valued function continuously differentiable in the segment $[0, a]$.

Theorem 1. *Let the following conditions hold:*

1) $\lambda^* \cdot \lambda_* < 0$ and $0 < \lambda \leq \mu < 1$;

$$2) \quad \sup_{(t,x) \in \overline{D}} \left| f(t, x, 0, 0, 0, \int_0^{h(t,x)} \psi(t, x, s, 0, 0, 0) ds) \right|$$

$$= \sup_{(t,x) \in \overline{D}} \max_{1 \leq i \leq n} \left| f_i(t, x, 0, 0, 0, \int_0^{h(t,x)} \psi(t, x, s, 0, 0, 0) ds) \right| = M_2 < \infty,$$

$$\sup_{(t,x) \in \overline{D}} |\psi(t, x, s, 0, 0, 0)| = \sup_{(t,x) \in \overline{D}} \max_{1 \leq i \leq n} |\psi_i(t, x, s, 0, 0, 0)| = M_3 < \infty,$$

$$|h(t, x)| \leq N, \quad |\varphi(x)| \leq M_1;$$

3) *the vector-valued functions $f(t, x, v_1, v_2, v_3, v_4, \psi(t, x, s, v_1, v_2, v_3))$ and their partial derivatives,*

$$\frac{\partial^{i_1+i_2} f(t, x, v_1, v_2, v_3, v_4)}{\partial x^{i_1} \partial v_j^{i_2}}, \quad \frac{\partial^{i_1+i_2} \psi(t, x, s, v_1, v_2, v_3)}{\partial x^{i_1} \partial v_k^{i_2}},$$

$$i_1 + i_2 = 1, \quad j = \overline{1, 4}, \quad k = \overline{1, 3},$$

are continuous with respect to all variables for every $(t, x) \in \overline{D}$, $v_1 \in \mathbb{R}^n$, $v_2 \in \mathbb{R}^n$, $v_3 \in \mathbb{R}^n$, $v_4 \in \mathbb{R}^1$ and satisfy the Lipschitz condition

$$|f(t, x, v'_1, v'_2, v'_3, v'_4) - f(t, x, v''_1, v''_2, v''_3, v''_4)|$$

$$\leq l(|v'_1 - v''_1| + |v'_2 - v''_2| + |v'_3 - v''_3| + |v'_4 - v''_4|),$$

$$\left| \frac{\partial^{i_1+i_2} f(t, x, v'_1, v'_2, v'_3, v'_4)}{\partial x^{i_1} \partial v_j^{i_2}} - \frac{\partial^{i_1+i_2} f(t, x, v''_1, v''_2, v''_3, v''_4)}{\partial x^{i_1} \partial v_j^{i_2}} \right|$$

$$\leq l(|v'_1 - v''_1| + |v'_2 - v''_2| + |v'_3 - v''_3| + |v'_4 - v''_4|),$$

$$|\psi(t, x, s, v'_1, v'_2, v'_3) - \psi(t, x, s, v''_1, v''_2, v''_3)|$$

$$\leq l^*(|v'_1 - v''_1| + |v'_2 - v''_2| + |v'_3 - v''_3|),$$

$$\left| \frac{\partial^{i_1+i_2}\psi(t, x, s, v'_1, v'_2, v'_3)}{\partial x^{i_1}\partial v_j^{i_2}} - \frac{\partial^{i_1+i_2}\psi(t, x, s, v''_1, v''_2, v''_3)}{\partial x^{i_1}\partial v_j^{i_2}} \right| \leq$$

$$\leq l^*(|v'_1 - v''_1| + |v'_2 - v''_2| + |v'_3 - v''_3|),$$

where $l, l^* = \text{const} > 0$,

$$(t, x, v'_1, v'_2, v'_3, v'_4), (t, x, v''_1, v''_2, v''_3, v''_4) \in \overline{D} \times \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^1 \rightarrow \mathbb{R}^n,$$

$$(t, x, s, v'_1, v'_2, v'_3), (t, x, s, v''_1, v''_2, v''_3) \in \overline{D} \times \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}^1 \rightarrow \mathbb{R}^n.$$

Then there exists a continuously differentiable solution of the problem (1), (2) in the domain \overline{D} .

Proof. First of all it is sufficient to show that there exists a solution of the system of integral equations of the form

$$u_i(t, x) = \varphi_i(x - \lambda_i t) + \int_0^t f_i(\tau, \lambda_i(\tau - t) + x, u(\tau, \lambda_i(\tau - t) + x),$$

$$u(\lambda\tau, \lambda_i(\tau - t) + x, u(\lambda\tau, \mu(\lambda_i(\tau - t) + x)),$$

$$\int_0^{h(t,x)} \psi(\tau, \lambda_i(\tau - t) + x), s, u(s, \lambda_i(\tau - t) + x), u(\lambda s, \lambda_i(\tau - t) + x),$$

$$u(\lambda s, \mu(\lambda_i(\tau - t) + x)) ds) d\tau, \quad (3)$$

which is continuously differentiable with respect to t and x in \overline{D} .

In order to construct a solution of the system (3), we can use the method of successive approximations. The successive approximations $u_i^m, i = \overline{1, n}, m = 0, 1, \dots$, are defined the following relations:

$$u_i^0(t, x) = 0,$$

$$u_i^m(t, x) = \varphi_i(x - \lambda_i t) + \int_0^t f_i(\tau, \lambda_i(\tau - t) + x, u^{m-1}(\tau, \lambda_i(\tau - t) + x),$$

$$u^{m-1}(\lambda\tau, \lambda_i(\tau - t) + x, u^{m-1}(\lambda\tau, \mu(\lambda_i(\tau - t) + x)),$$

$$\int_0^{h(\tau, x - \lambda_i t)} \psi(\tau, \lambda_i(\tau - t) + x), s, u^{m-1}(s, \lambda_i(\tau - t) + x), u^{m-1}(\lambda s, \lambda_i(\tau - t) + x),$$

$$u^{m-1}(\lambda s, \mu(\lambda_i(\tau - t) + x)) ds) d\tau, \quad i = \overline{1, n}, \quad m = 1, 2, \dots \quad (4)$$

We shall show that the sequences of the continuous functions $u_i^m(t, x), i = \overline{1, n}, m = 0, 1, \dots$, uniformly converge to some continuous functions $u_i(t, x), i = \overline{1, n}$, for every $(t, x) \in \overline{D}$. It is sufficient to show that the following estimates hold:

$$|u_i^m(t, x) - u_i^{m-1}(t, x)| \leq M \frac{(3lQt)^{m-1}}{(m-1)!}, \quad i = \overline{1, n}, \quad \text{where } M, Q = \text{const} > 0, \quad (5)$$

for every $(t, x) \in \overline{D}$ and $m \geq 1$.

Condition 2), for $m = 1$ and (3), implies that

$$|u_i^1(t, x) - u_i^0(t, x)| \leq |\varphi_i(x - \lambda_i t)| + \int_0^t \left| f_i(\tau, \lambda_i(\tau - t) + x, 0, 0, 0), \right.$$

$$\left. \int_0^{h(\tau, x - \lambda_i t)} \psi(\tau, \lambda_i(\tau - t) + x), s, 0, 0, 0) ds \right| d\tau \leq M_1 + M_2 t = M.$$

In this case the condition (5) is satisfied.

Suppose that the condition (5) holds for some $m \geq 1$ and show that it will be the same if we pass from m to $m + 1$. Indeed, in view of (4), 2), 3), and (5), we have

$$|u_i^m(t, x) - u_i^{m-1}(t, x)| \leq \int_0^t \left| f_i(\tau, \lambda_i(\tau - t) + x, u^m(\tau, \lambda_i(\tau - t) + x), \right.$$

$$u^m(\lambda\tau, \lambda_i(\tau - t) + x), u^m(\lambda\tau, \mu(\lambda_i(\tau - t) + x)),$$

$$\left. \int_0^{h(\tau, x - \lambda_i t)} \psi(\tau, \lambda_i(\tau - t) + x), s, u^m(s, \lambda_i(\tau - t) + x), u^m(\lambda s, \lambda_i(\tau - t) + x), \right.$$

$$u^m(\lambda s, \mu(\lambda_i(\tau - t) + x)) ds) - f_i(\tau, \lambda_i(\tau - t) + x, u^{m-1}(\tau, \lambda_i(\tau - t) + x),$$

$$u^{m-1}(\lambda\tau, \lambda_i(\tau - t) + x), u^{m-1}(\lambda\tau, \mu(\lambda_i(\tau - t) + x)),$$

$$\int_0^{h(t,x)} \psi(\tau, \lambda_i(\tau - t) + x), s, u^{m-1}(s, \lambda_i(\tau - t) + x), u^{m-1}(\lambda s, \lambda_i(\tau - t) + x),$$

$$u^{m-1}(\lambda s, \mu(\lambda_i(\tau - t) + x)) ds \Big| d\tau$$

$$\leq \int_0^t l(|u^m(\tau, \lambda_i(\tau - t) + x) - u^{m-1}(\tau, \lambda_i(\tau - t) + x)|$$

$$+ |u^m(\lambda\tau, \lambda_i(\tau - t) + x) - u^{m-1}(\lambda\tau, \lambda_i(\tau - t) + x)|$$

$$+ |u^m(\lambda\tau, \mu(\lambda_i(\tau - t) + x)) - u^{m-1}(\lambda\tau, \mu(\lambda_i(\tau - t) + x))|$$

$$+ \int_0^{h(\tau, x - \lambda_i t)} l^*(|u^m(s, \lambda_i(\tau - t) + x) - u^{m-1}(s, \lambda_i(\tau - t) + x)|$$

$$+ |u^m(\lambda s, \lambda_i(\tau - t) + x) - u^{m-1}(\lambda s, \lambda_i(\tau - t) + x)|$$

$$+ |u^m(\lambda s, \mu(\lambda_i(\tau - t) + x)) - u^{m-1}(\lambda s, \mu(\lambda_i(\tau - t) + x))|) ds) d\tau \leq M \frac{(3lQt)^m}{m!},$$

where $Q = 1 + l^*N$. Thus, condition (5) is satisfied for every $(t, x) \in \overline{D}$ and $m \geq 1$. From this it follows that the series

$$\sum_{m=1}^{\infty} (u_i^m(t, x) - u_i^{m-1}(t, x)), \quad i = \overline{1, n},$$

and, the sequences $u_i^m(t, x), i = \overline{1, n}$, are uniformly convergent to some continuous functions $u_i(t, x), i = \overline{1, n}$, with respect to t, x for every $(t, x) \in \overline{D}$.

Passing to the limit as $m \rightarrow \infty$ in (4), we can verify that the functions $u_i(t, x), i = \overline{1, n}$, are solution of the system (3).

Let us prove that the obtained solution is continuously differentiable with respect to t, x for every $(t, x) \in \overline{D}$. It is sufficient to show that the sequences of functions $\partial u_i^m(t, x)/\partial x, \partial u_i^m(t, x)/\partial t, i = \overline{1, n}, m = 0, 1, \dots$, are uniformly convergent to some continuous functions $u_i^m(t, x)$ with respect to t, x for every $(t, x) \in \overline{D}$.

In view of (4), we have

$$\frac{\partial u_i^0(t, x)}{\partial x} = 0,$$

$$\begin{aligned} \frac{\partial u_i^m(t, x)}{\partial x} = & \varphi'(x - \lambda_i t) + \int_0^t \left(\frac{\partial f_i(m-1)}{\partial x} + \frac{\partial f_i(m-1)}{\partial v_1} \frac{\partial u^{m-1}(\tau, \lambda_i(\tau - t) + x)}{\partial x} \right. \\ & + \frac{\partial f_i(m-1)}{\partial v_2} \frac{\partial u^{m-1}(\lambda\tau, \lambda_i(\tau - t) + x)}{\partial x} \\ & + \mu \frac{\partial f_i(m-1)}{\partial v_3} \frac{\partial u^{m-1}(\lambda\tau, \mu(\lambda_i(\tau - t) + x))}{\partial x} \\ & + \frac{\partial f_i(m-1)}{\partial v_4} \left(\int_0^{h(\tau, x - \lambda_i t)} \left(\frac{\partial \psi_i(m-1)}{\partial x} + \frac{\partial \psi_i(m-1)}{\partial v_1} \frac{\partial u^{m-1}(s, \lambda_i(\tau - t) + x)}{\partial x} \right. \right. \\ & + \frac{\partial f_i(m-1)}{\partial v_2} \frac{\partial u^{m-1}(\lambda s, \lambda_i(\tau - t) + x)}{\partial x} \\ & \left. \left. + \mu \frac{\partial \psi_i(m-1)}{\partial v_3} \frac{\partial u^{m-1}(\lambda s, \mu(\lambda_i(\tau - t) + x))}{\partial x} \right) ds \right) \right) d\tau, \end{aligned}$$

$$\frac{\partial u_i^0(t, x)}{\partial t} = 0,$$

$$\frac{\partial u_i^m(t, x)}{\partial t} = -\lambda_i \varphi'(x - \lambda_i t) + f_i(\tau, \lambda_i(\tau - t) + x, u^{m-1}(\tau, \lambda_i(\tau - t) + x),$$

$$u^{m-1}(\lambda\tau, \lambda_i(\tau - t) + x), u^{m-1}(\lambda\tau, \mu(\lambda_i(\tau - t) + x)),$$

$$\int_0^{h(\tau, x - \lambda_i t)} \psi_i(\tau, \lambda_i(\tau - t) + x, s, u^{m-1}(s, \lambda_i(\tau - t) + x),$$

$$\begin{aligned}
& u^{m-1}(\lambda s, \lambda_i(\tau - t) + x), u^{m-1}(\lambda s, \mu(\lambda_i(\tau - t) + x))) ds \\
& - \lambda_i \int_0^t \left(\frac{\partial f_i(m-1)}{\partial x} + \frac{\partial f_i(m-1)}{\partial v_1} \frac{\partial u^{m-1}(\tau, \lambda_i(\tau - t) + x)}{\partial x} \right. \\
& + \frac{\partial f_i(m-1)}{\partial v_2} \frac{\partial u^{m-1}(\lambda \tau, \lambda_i(\tau - t) + x)}{\partial x} \\
& + \mu \frac{\partial f_i(m-1)}{\partial v_3} \frac{\partial u^{m-1}(\lambda \tau, \mu(\lambda_i(\tau - t) + x))}{\partial x} \\
& + \left. \frac{\partial f_i(m-1)}{\partial v_4} \left(\psi_i(\tau, \lambda_i(\tau - t) + x, s, u^{m-1}(s, \lambda_i(\tau - t) + x)), \right. \right. \\
& \quad \left. \left. u^{m-1}(\lambda s, \lambda_i(\tau - t) + x), u^{m-1}(\lambda s, \mu(\lambda_i(\tau - t) + x)) \right) \right) ds \\
& + \int_0^{h(\tau, x - \lambda_i t)} \left(\frac{\partial \psi_i(m-1)}{\partial x} + \frac{\partial \psi_i(m-1)}{\partial v_1} \frac{\partial u^{m-1}(s, \lambda_i(\tau - t))}{\partial x} \right. \\
& + \frac{\partial \psi_i(m-1)}{\partial v_2} \frac{\partial u^{m-1}(\lambda s, \lambda_i(\tau - t))}{\partial x} \\
& + \left. \left. \mu \frac{\partial \psi_i(m-1)}{\partial v_3} \frac{\partial u^{m-1}(\lambda s, \mu(\lambda_i(\tau - t)))}{\partial x} \right) ds \right) d\tau,
\end{aligned}$$

where

$$\begin{aligned}
f_i(m-1) &= \psi_i(\tau, \lambda_i(\tau - t) + x, u^{m-1}(\tau, \lambda_i(\tau - t) + x), u^{m-1}(\lambda \tau, \lambda_i(\tau - t) + x), \\
& u^{m-1}(\lambda \tau, \mu(\lambda_i(\tau - t) + x)), \int_0^{h(\tau, x - \lambda_i t)} \psi(\tau, \lambda_i(\tau - t) + x, s, u^{m-1}(\tau, \lambda_i(\tau - t) + x), \\
& u^{m-1}(\lambda \tau, \mu(\lambda_i(\tau - t) + x))) ds).
\end{aligned}$$

Now, it is sufficient to prove that only sequences

$$\frac{\partial u_i^m(t, x)}{\partial x}, \quad i = \overline{1, n}, \quad m = 0, 1, \dots,$$

are uniformly convergent for every $(t, x) \in \bar{D}$.

Let us prove that the following relations hold:

$$\left| \frac{\partial u_i^m(t, x)}{\partial x} - \frac{\partial u_i^{m-1}(t, x)}{\partial x} \right| \leq Z \frac{(KtQ)^{m-1}}{(m-1)!}, \tag{6}$$

for every $(t, x) \in \bar{D}$ and $m \geq 1$, where Q, K, Z are some positive numbers.

As a consequence of (5), we have

$$\begin{aligned} |u_i^m(t, x)| &\leq |u_i^0(t, x)| + |u_i^1(t, x) - u_i^0(t, x)| \\ &+ \dots + |u_i^m(t, x) - u_i^{m-1}(t, x)| \leq \sum_{j=1}^{\infty} |u_i^j(t, x) - u_i^{j-1}(t, x)| \\ &\leq M \sum_{j=1}^{\infty} \frac{(3lTQ)^{j-1}}{(j-1)!}, \quad i = \overline{1, n}, \end{aligned}$$

for every $m \geq 1$ and $(t, x) \in \bar{D}$, where T is some positive number larger than an arbitrary value of t from the bounded domain \bar{D} and such that the number series $\sum_{j=1}^{\infty} \frac{(3lTQ)^{j-1}}{(j-1)!}$ is convergent. Then we have

$$|u_i^m(t, x)| \leq \widetilde{M}, \quad i = \overline{1, n}, \quad \widetilde{M} = \text{const} > 0, \tag{7}$$

for every $(t, x) \in \bar{D}$ and $m \geq 1$.

Analogously, if relations (6) hold, then we have the following inequalities for every $(t, x) \in \bar{D}$:

$$\left| \frac{\partial u_i^m(t, x)}{\partial x} \right| \leq \widetilde{N}, \quad i = \overline{1, n}, \quad \widetilde{N} = \text{const} > 0. \tag{8}$$

Denote by

$$L_1 = \sup_D \max_{i,j} \left| \frac{\partial f_i(t, x, v_1, v_2, v_3, v_4)}{\partial v_j} \right|, \tag{9}$$

$$L^* = \sup_D \max_{i,j} \left| \frac{\partial \psi_i(t, x, s, v_1, v_2, v_3)}{\partial v_j} \right|, \tag{10}$$

$$\bar{N} = \sup_D \max_i \left| \frac{\partial u_i^m(t, x)}{\partial x} \right|, \tag{11}$$

$$L^{**} = \sup_D \max_i \left| \frac{\partial v_4}{\partial x} \right|, \tag{12}$$

where $D = \{(t, x, v_1, v_2, v_3, v_4) : (t, x) \in \bar{D}, |v_1| \leq \widetilde{M}, |v_2| \leq \widetilde{M}, |v_3| \leq \widetilde{M}, |v_4| \leq S\}$.

Taking into account (1) and (9) we have

$$\begin{aligned} \left| \frac{\partial u_i^1(t, x)}{\partial x} - \frac{\partial u_i^0(t, x)}{\partial x} \right| &\leq |\psi'_i(x - \lambda_i t)| \\ &+ \int_0^t \left| \frac{\partial f_i}{\partial x}(\tau, \lambda_i(\tau - t) + x, 0, 0, 0, \frac{\partial f_i}{\partial v_4} \int_0^{h(\tau, x - \lambda_i t)} \frac{\partial \psi_i}{\partial x}(\tau, \lambda_i(\tau - t) + x, s, 0, 0, 0) ds) \right| d\tau \\ &\leq L_2 + L_1 t < L_2 + L_1 T = Z, \end{aligned}$$

therefore, condition (6) holds for $m = 1$. Reasoning by induction, suppose that condition (6) is proved for some $m \geq 1$ and show that this condition is the same after passing from m to $m + 1$.

Indeed, using (5), conditions 2) and 3) of the theorem and (4), (5), (9), (11) we have

$$\begin{aligned} &\left| \frac{\partial u_i^m(t, x)}{\partial x} - \frac{\partial u_i^{m-1}(t, x)}{\partial x} \right| \\ &\leq 3lM \frac{(3lQ)^{m-1}}{(m-1)!} \int_0^t \tau^{m-1} d\tau + 3ll^*MN \frac{(3lQ)^{m-1}}{(m-1)!} \int_0^t \tau^{m-1} d\tau \\ &\quad + (3l\bar{N} + L^{**}) \left(3M \frac{(3lQ)^{m-1}}{(m-1)!} \int_0^t \tau^{m-1} d\tau + 3l^*NM \frac{(3lQ)^{m-1}}{(m-1)!} \int_0^t \tau^{m-1} d\tau \right) \\ &\quad + 3L_1Z \frac{(KQ)^{m-1}}{(m-1)!} \int_0^t \tau^{m-1} d\tau + L_1Z \frac{(KQ)^{m-1}}{(m-1)!} \int_0^t \tau^{m-1} d\tau \\ &= Z \frac{(QKt)^m}{m!} \left(\frac{M}{ZQ} \left(\frac{3l}{K} \right)^m + \frac{(NMI^*)}{ZQ} \left(\frac{3l}{K} \right)^m + \frac{3\bar{N}M}{ZQ} \left(\frac{3l}{K} \right)^m \right. \\ &\quad \left. + \frac{3\bar{N}MNl^*}{ZQ} \left(\frac{3l}{K} \right)^m + \frac{L^{**}M}{ZQ} \left(\frac{3l}{K} \right)^m + \frac{L^{**}l^*NM}{ZQ} \left(\frac{3l}{K} \right)^m + \frac{3L_1}{QK} + \frac{L_1}{QK} \right). \end{aligned}$$

From this it follows that, for sufficiently large K, Q , the inequality

$$\begin{aligned} & \frac{M}{ZQ} \left(\frac{3l}{K} \right)^m + \frac{NMl^*}{ZQ} \left(\frac{3l}{K} \right)^m + \frac{3\bar{N}M}{ZQ} \left(\frac{3l}{K} \right)^m + \frac{3\bar{N}MNl}{ZQ} \left(\frac{3l}{K} \right)^m \\ & + \frac{L^{**}M}{ZQ} \left(\frac{3l}{K} \right)^m + \frac{L^{**}l^*NM}{ZQ} \left(\frac{3l}{K} \right)^m + \frac{3L_1}{QK} + \frac{L_1}{QK} < 1 \end{aligned}$$

holds and, therefore, condition (6) is true.

From (6) it directly follows that the sequences $\partial u_i^m(t, x)/\partial x, i = \overline{1, n}, m = 0, 1, \dots$, are uniformly convergent to continuous functions $\partial u_i(t, x)/\partial x, i = \overline{1, n}$, for every $(t, x) \in \bar{D}$. This completes the proof of theorem.

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