

On Integrability of Some Nonlinear Model with Variable Separant

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In this paper a new integrable nonlinear Hamiltonian system in $(1 + 1)$ -dimension is introduced. Nontrivial connection with well-known multicomponent nonlinear Schrödinger model is found.

Let us consider a non-linear Hamiltonian system

$$\psi_t = \{\psi, H\} \tag{1}$$

in the Schwarz space of smooth fast decreasing on the $\pm\infty$ complex value l -component vector-functions $\psi = (\psi_1, \dots, \psi_l)(x)$, $l \in \mathbb{N}$ of the variable $x \in \mathbb{R}$ with the Hamiltonian

$$H = \int_{-\infty}^{+\infty} |\psi_x|^2 dx, \tag{2}$$

and local brackets of Poisson for dynamic variables $\psi_m, \bar{\psi}_n$, $m, n = \overline{1, l}$:

$$\{\psi_n(x), \bar{\psi}_m(y)\} := i\delta_n^m (c + |\psi|^2(x))^2 \delta(x - y), \tag{3}$$

where δ_n^m is the Kronecker symbol, $\delta(z)$ is the Dirac function, $c \in \mathbb{R}$.

System (1) is non-linear evolutionary system of differential equations with variable separant (coefficient at higher derivative) and has the next form:

$$i\psi_t = - (c + |\psi|^2)^2 \frac{\delta H}{\delta \bar{\psi}^*} = (c + |\psi|^2)^2 \psi_{xx}, \tag{4}$$

where $\frac{\delta}{\delta \bar{\psi}^*}$ is the Euler operator of variative derivative over the vector-function $\psi^* := \bar{\psi}^\top$.

Proposition 1. *Hamiltonian system (1)–(4) is formally integrable (by Lax) and assumes infinite hierarchy non-trivial local laws of motion.*

Proof. For simplicity we restrict ourselves with Lax commutative representation discovered by us $[L, M] := LM - ML = 0$ in algebra of integro-differential operators [1, 2] which is equivalent to system (4), where

$$L = (c + |\psi|^2) \mathcal{D} + \psi_x \psi^* - \psi_x \mathcal{D}^{-1} \psi_x^*, \tag{5}$$

$$M = i\partial_t - (c + |\psi|^2)^2 \mathcal{D}^2 - 2(c + |\psi|^2) |\psi|_x^2 \mathcal{D} = i\partial_t - (L^2)_{>0}, \tag{6}$$

and, as consequence of operators commutativity in (5)–(6), known [1] procedure for finding density ρ_k of first integrals $H_k := \int_{-\infty}^{+\infty} \rho_k dx$:

$$\rho_k = \text{Res} \left(L^k \right), \quad k \in \mathbb{Z}. \tag{7}$$

■

Remark 1. Obviously, $k = 1$ corresponds to Hamiltonian $H(2)$, and one of the simplest first integrals ($k = -1$) in the formula (7) has the form:

$$H_{-1} = \int_{-\infty}^{+\infty} \frac{|\psi|^2}{c + |\psi|^2} dx, \quad c \in \mathbb{R} \setminus \{0\}.$$

Remark 2. In the formula (5) integral item $\psi_x \mathcal{D}^{-1} \psi_x^*$ is a symbol of skew-Hermitian operator of Volterra \widehat{V} with the degenerated kernel $V(x, s) := \frac{\partial \psi(x)}{\partial x} \frac{\partial \psi^*(s)}{\partial s}$

$$(\widehat{V}f)(x) = \frac{1}{2} \left\{ \int_{-\infty}^x \sum_{i=1}^l \frac{\partial \psi_i(x)}{\partial x} \frac{\partial \bar{\psi}_i(s)}{\partial s} f(s) ds - \int_x^{+\infty} \sum_{i=1}^l \frac{\partial \psi_i(x)}{\partial x} \frac{\partial \bar{\psi}_i(s)}{\partial s} f(s) ds \right\}.$$

The symbol $(L^k)_{>0}$ stands for the differential part without free term (multiplier operator by function) of an integro-differential operator L^k .

Proposition 2. *The following non-local replacement of variables $(t, x, \psi) \rightarrow (\tau, y, \varphi)$:*

$$\tau = t, \quad y'_x = \frac{1}{c + |\psi|^2}, \quad \varphi(\tau, y) = \frac{\psi_y}{c + |\psi|^2} \exp \int_{-\infty}^y \frac{\psi_y \psi^*}{c + |\psi|^2} dy \quad (8)$$

transforms non-linear system (4) into the multicomponent non-linear equation of Schrödinger [3]

$$i\varphi_\tau = \varphi_{xx} + 2|\varphi|^2 \varphi. \quad (9)$$

Proof. The proof is conducted by direct calculation. We restrict ourselves by the Lax operator (5). Making replacement (8) we get

$$L = (c + |\psi|^2) \mathcal{D}_x + \psi_x \psi^* - \psi_x \mathcal{D}_x^{-1} \psi^* \rightarrow \widetilde{L} = \mathcal{D}_y + \frac{\psi_y \psi^*}{c + |\psi|^2} - \frac{\psi_y}{c + |\psi|^2} \mathcal{D}_y^{-1} \psi_y^*,$$

and after gauge transformation $\widetilde{L} \rightarrow \Phi \widetilde{L} \Phi^{-1}$ with the function $\Phi = \exp \int_{-\infty}^y \frac{\psi_y \psi^*}{c + |\psi|^2} dy$ the operator L to pass into the Lax operator L_{NS} [2, 4, 5] for the model (9):

$$L_{NS} = \Phi \widetilde{L} \Phi^{-1} = \mathcal{D}_y - \varphi \mathcal{D}^{-1} \varphi^*,$$

where the dynamic variable $\varphi = \varphi(\tau, y)$ is defined by substitution (8). ■

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