

# On One Problem of Automatic Control with Turning Points

Valentin LEIFURA

Mykolaiv Teachers Training Institute, Mykolaiv, Ukraine

## Abstract

An algorithm for solutions of one problem of automatic control is suggested for the case of an interval containing turning points.

Let us consider an equation of the form

$$\varepsilon^2 \frac{d^2 x(t, \varepsilon)}{dt^2} + \varepsilon a(\tau, \varepsilon) \frac{dx(t, \varepsilon)}{dt} + b(\tau, \varepsilon) x(t, \varepsilon) = \varepsilon h(\tau) \int_{-\infty}^t G(t-t', \tau') x(t', \varepsilon) dt', \quad (1)$$

where  $\varepsilon$  is a small parameter,  $\varepsilon \in (0; \varepsilon_0]$ ,  $\varepsilon_0 \leq 1$ ,  $\tau = \varepsilon t$ ,  $t \in [0, L]$ . The left-hand side of the equation defines automatic control, where  $G(t-t', \tau')$  is the impulse transfer function of a regulator. Functions  $a(\tau, \varepsilon)$ ,  $b(\tau, \varepsilon)$  admit the following decomposition:

$$a(\tau, \varepsilon) = \sum_{i=0}^{\infty} \varepsilon^i a_i(\tau), \quad b(\tau, \varepsilon) = \sum_{i=0}^{\infty} \varepsilon^i b_i(\tau). \quad (2)$$

In papers [1–2], automatic control systems described by equation (1) were studied in detail, but turning points were not considered. It was assumed that the characteristic equation, i.e., the equation

$$\lambda_0^2(\tau) + a_0(\tau) \lambda_0(\tau) + b_0(\tau) = 0, \quad (3)$$

has two roots for all  $\tau \in [0, \varepsilon L]$ .

For the case where equation (1) is considered on the interval  $[\alpha, \beta]$ , which does not contain any turning points, the following theorem is true:

**Theorem 1.** *If functions  $a_i(\tau)$ ,  $b_i(\tau)$  are continuous and differentiable infinite number of times on  $[\varepsilon\alpha, \varepsilon\beta]$  and  $a_0^2(\tau) - 4b_0(\tau) \neq 0$ , then, on the interval  $[\alpha, \beta]$ , equation (1) has two linearly independent formal solutions of the form*

$$x_1(t, \varepsilon) = \exp\left(\frac{1}{\varepsilon} \int_{\alpha}^t \varphi_1(\tau', \varepsilon) dt'\right), \quad \varphi_1(\tau, \varepsilon) = \sum_{i=0}^{\infty} \varepsilon^i \varphi_{1i}(\tau), \quad (4)$$

$$x_2(t, \varepsilon) = \exp\left(\frac{1}{\varepsilon} \int_{\alpha}^t \varphi_2(\tau', \varepsilon) dt'\right), \quad \varphi_2(\tau, \varepsilon) = \sum_{i=0}^{\infty} \varepsilon^i \varphi_{2i}(\tau), \quad (5)$$

where  $\varphi_{1i}(\tau), \varphi_{2i}(\tau)$  are continuous and infinitely differentiable on  $[\varepsilon\alpha, \varepsilon\beta]$ .

An algorithm for determination of functions  $\varphi_{1i}(\tau), \varphi_{2i}(\tau)$  is adduced in [2]. Along with equation (1), we consider also the following auxiliary equation

$$\begin{aligned} \frac{d^2 z(\xi, \mu)}{d\xi^2} + \tilde{a}(\eta, \mu) \frac{dz(\xi, \mu)}{d\xi} + \tilde{b}(\eta, \mu) z(\xi, \mu) = \\ = \mu \tilde{h}(\eta, \mu) \int_{-\infty}^{\xi} G((\xi - \xi')\mu, \mu^2 t_0 + \mu\eta') z(\xi', \mu) d\xi', \end{aligned} \tag{6}$$

where  $\xi \in [\alpha; \beta], \mu \in (0; \mu_0), \eta = \xi\mu^2, t_0 \in [\alpha\mu; \beta\mu]$ , and functions  $\tilde{a}(\eta, \mu), \tilde{b}(\eta, \mu), \tilde{h}(\eta, \mu)$  admit the following decomposition:

$$\tilde{a}(\eta, \mu) = \sum_{i=0}^{\infty} \mu^i \tilde{a}_i(\eta), \quad \tilde{b}(\eta, \mu) = \sum_{i=0}^{\infty} \mu^i \tilde{b}_i(\eta), \quad \tilde{h}(\eta, \mu) = \sum_{i=0}^{\infty} \mu^i \tilde{h}_i(\eta).$$

**Theorem 2.** *If functions  $\tilde{a}_i(\eta), \tilde{b}_i(\eta), \tilde{h}_i(\eta)$  are infinitely differentiable on the interval  $[\alpha\mu^2\beta\mu^2]$  and  $\tilde{a}_0^2(\eta) - 4\tilde{b}_0(\eta) \neq 0$ , then, on the interval  $[\alpha, \beta]$ , equation (6) has two linearly independent formal solutions of the form*

$$\begin{aligned} z_1(\xi, \mu) = \exp\left(\int_{\alpha}^{\xi} \lambda_1(\eta', \mu) d\xi'\right), \quad \lambda_1(\eta, \mu) = \sum_{i=0}^{\infty} \mu^i \lambda_{1i}(\eta), \\ z_2(\xi, \mu) = \exp\left(\int_{\alpha}^{\xi} \lambda_2(\eta', \mu) d\xi'\right), \quad \lambda_2(\eta, \mu) = \sum_{i=0}^{\infty} \mu^i \lambda_{2i}(\eta), \end{aligned}$$

where  $\lambda_{1i}(\tau), \lambda_{2i}(\tau)$  are infinitely differentiable functions on  $[\mu^2\alpha, \mu^2\beta]$ .

The proof of this theorem is similar to that of Theorem 1.

Let us go back to the consideration of equation (1) under condition of the existence of a zero turning point. Let functions  $a_0(\tau), b_0(\tau)$  have the form  $a_0 = \tau a_{10}(\tau), b_0 = \tau^2 b_{10}(\tau)$ . Then roots of the characteristic equation have the form

$$\lambda_{1,2}(\tau) = -\frac{1}{2}\tau \left( a_{10}(\tau) \pm \sqrt{a_{10}^2(\tau) - 4b_{10}(\tau)} \right). \tag{7}$$

If  $a_{10}^2(\tau) - 4b_{10}(\tau) \neq 0 \forall t \in (0; L]$ , then  $t = 0$  is a zero turning point.

Let us consider the Cauchy problem for equation (1) with the initial conditions

$$x(\beta\sqrt{\varepsilon}, \varepsilon) = y_{10}, \quad \left. \frac{dx}{dt} \right|_{t=\beta\sqrt{\varepsilon}} = y_{20}, \tag{8}$$

where  $\beta$  is a real number,  $y_{10}$  and  $y_{20}$  are quantities which do not depend on  $\varepsilon$ .

First using Theorem 1 for the case  $t \in [\beta\sqrt{\varepsilon}, L]$ , we construct the  $m$ -approximation for a general solution of equation (1) using the formula

$$x_m^{(2)}(t, \varepsilon) = a_1^{(2)}(\varepsilon)x_{1m}(t, \varepsilon) + a_2^{(2)}(\varepsilon)x_{2m}(\varepsilon),$$

where

$$x_m^{(2)}(t, \varepsilon) = \exp \left( \frac{1}{\varepsilon} \int_{\beta\sqrt{\varepsilon}}^t \left( \sum_{i=0}^m \varepsilon^i \varphi_{ki}(\tau) \right) dt' \right), \quad k = 1, 2,$$

$a_k^{(2)}(\varepsilon)$ ,  $k = 1, 2$  are arbitrary constants which are determined from condition (8).

Finally we construct a solution of equation (1) within the vicinity of a turning point or when  $t \in [0, \beta\sqrt{\varepsilon}]$ .

After the substitution  $t = \xi\sqrt{\varepsilon}$  ( $\xi \in [0, \beta)$ ) using the notations  $\mu = \sqrt{\varepsilon}$ ,  $\xi\mu^2 = \eta$ ,  $x = z(\xi, \mu)$  equation (1) takes the form

$$\begin{aligned} \frac{d^2 z(\xi, \mu)}{d\xi^2} + \eta a_{10}(\eta\mu) + \sum_{i=1}^{\infty} \mu^{2i-1} a_i(\eta\mu) \frac{dz(\xi, \mu)}{d\xi} + \\ + \left( \eta^2 b_{10}(\eta\mu) + \sum_{i=1}^{\infty} b_i(\eta\mu) \mu^{2i-2} \right) z(\xi, \mu) = \\ = \mu h(\eta\mu) \int_{-\infty}^{\xi} G((\xi - \xi')\mu, \eta'\mu) z(\xi', \mu) d\xi'. \end{aligned} \tag{9}$$

Let us assume that the coefficients  $a_{10}(\tau)$ ,  $b_{10}(\tau)$ ,  $a_i(\tau)$ ,  $b_i(\tau)$ ,  $i = 1, \dots, 8$ , and function  $h(\tau)$  can be decomposed into a Taylor series within the neighbourhood of the point  $\tau = 0$ . Then

$$\begin{aligned} a_{10}(\eta\mu) = a_{10}(0) + \sum_{i=1}^{\infty} \mu^i \frac{a_{10}^{(i)}(0)}{i!} \eta^i, \quad a_i(\eta\mu) = a_i(0) + \sum_{j=1}^{\infty} \mu^j \frac{a_i^{(j)}(0)}{j!} \eta^j, \\ \sum_{i=1}^{\infty} \mu^{2i-1} a_i(\eta\mu) = \sum_{i=1}^{\infty} \sum_{j=0}^{\infty} \mu^{2i+j-1} \frac{a_i^{(j)}(0)}{j!} \eta^j = \sum_{i=1}^{\infty} \mu^i \tilde{a}_i(\eta), \end{aligned}$$

whence

$$\eta a_{10}(\eta\mu) + \sum_{i=1}^{\infty} \mu^{2i-1} a_i(\eta\mu) = \eta a_{10}(0) + \sum_{i=1}^{\infty} \mu^i \tilde{a}_i(\eta). \tag{10}$$

Similarly, we get

$$\eta^2 b_{10}(\eta\mu) + \sum_{i=1}^{\infty} \mu^{2i-2} b_i(\eta\mu) = b_{10}(0)\eta^2 + \sum_{i=1}^{\infty} \mu^i \tilde{b}_i(\eta) + b_1(0). \tag{11}$$

Finally, for  $h(\eta\mu)$ , we have

$$h(\eta\mu) = \sum_{i=1}^{\infty} \frac{h^{(i)}(0)}{i!} (\eta\mu)^i = \sum_{i=1}^{\infty} \mu^i \tilde{h}_i(\eta). \tag{12}$$

Substituting (10)–(12) into (9), we get

$$\begin{aligned} \frac{d^2 z(\xi, \mu)}{d\xi^2} + \left( \eta a_{10}(0) + \sum_{i=1}^{\infty} \mu^i \tilde{a}_i(\eta) \right) \frac{dz(\xi, \mu)}{d\xi} + \\ + \left( b_{10}(0)\eta^2 + b_1(0) + \sum_{i=1}^{\infty} \mu^i \tilde{b}_i(\eta) \right) z(\xi, \mu) = \\ = \mu \sum_{i=1}^{\infty} \mu^i \tilde{h}_i(\eta) \int_{-\infty}^{\xi} G((\xi - \xi')\mu, \eta' \mu) z(\xi', \mu) d\xi'. \end{aligned} \quad (13)$$

If  $\forall \xi \in [0, \beta]$   $\eta^2(a_{10}^2(0) - 4b_{10}(0)) - 4b_1(0) \neq 0$ , then, according to Theorem 2, equation (13) has the general solution, the  $m$ -approximation of which can be constructed using the formula

$$x_m^{(1)}(t, \varepsilon) = a_1^{(1)}(\xi) x_{1m}^{(1)}(t, \varepsilon) + a_2^{(1)}(\xi) x_{2m}^{(1)}(t, \varepsilon), \quad t \in [0, \beta\sqrt{\varepsilon}],$$

where

$$\begin{aligned} x_{km}^{(1)}(t, \varepsilon) = \exp \left( \frac{1}{\sqrt{\varepsilon}} \int_{\beta\sqrt{\varepsilon}}^t \lambda_{km} \left( \frac{\tau'}{\sqrt{\varepsilon}}, \sqrt{\varepsilon} \right) dt' \right), \quad k = 1, 2, \\ \lambda_{km} \left( \frac{\tau}{\sqrt{\varepsilon}}, \sqrt{\varepsilon} \right) = \sum_{i=m}^m (\sqrt{\varepsilon})^i \lambda_{ki} \left( \frac{\tau}{\sqrt{\varepsilon}} \right). \end{aligned}$$

The constants  $a_1^{(1)}(\varepsilon)$ ,  $a_2^{(1)}(\varepsilon)$  are determined as solutions of the system  $x_m^{(1)}(\beta\sqrt{\varepsilon}, \varepsilon) = y_{10}$ ,  $dx_m^{(1)}|_{t=\beta\sqrt{\varepsilon}} = y_{20}$ . Thus, for equation (1) with a zero turning point, we have constructed a continuous (together with its derivative)  $m$ -approximation of the solution

$$x_m(t, \varepsilon) = \begin{cases} x_m^{(1)}(t, \varepsilon), & t \in [0, \beta\sqrt{\varepsilon}], \\ x_m^{(2)}(t, \varepsilon), & t \in [\beta\sqrt{\varepsilon}, L], \end{cases}$$

which satisfies the initial conditions (8).

Asymptotic character of the solution obtained (as defined in [3]) is established by using the methods suggested in [4].

## References

- [1] Abgaryan K.A., Matrix and Asymptotic Methods in the Theory of Linear Systems, Moscow, Nauka, 1973.
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